Intuitionistic layered graph logic*

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Abstract

Models of complex systems are widely used in the physical and social sciences, and the concept of layering, typically building upon graph-theoretic structure, is a common feature. We describe an intuitionistic substructural logic that gives an account of layering. As in other bunched systems, the logic includes the usual intuitionistic connectives, together with a non-commutative, non-associative conjunction (used to capture layering) and its associated implications. We give a soundness and completeness theorem for a labelled tableaux system with respect to a Kripke semantics on graphs. To demonstrate the utility of the logic, we show how to represent systems and security examples, illuminating the relationship between services/policies and the infrastructures/architectures to which they are applied.

1 Introduction

Complex systems is the field of science that studies, on the one hand, how it is that the behaviour of a system, be it natural or synthetic, derives from the behaviours of its constituent parts and, on the other, how the system interacts with its environment. A commonly employed and highly effective concept that helps to manage the difficulty in conceptualizing and reasoning about complex systems is that of *layering*: the system is considered to consist of a collection of interconnected layers each of which has a distinct, identifiable role in the system's operations. Layers can be informational or physical and both kinds may be present in a specific system.

Graphs provide a suitably abstract setting for a wide variety of modelling purposes, and layered graphs already form a component of existing systems modelling approaches. For example, both social networks [Bródka *et al.*, 2011] and transportation systems [Kurant and Thiran, 2006], have been modelled by a form of layered graph in which multiple layers are given by relations over a single set of vertices. Elsewhere layered graph models have been deployed to solve problems related to telecommunications networks [Gouveia

et al., 2011] and to aid the design of P2P systems for businesses [Wang et al., 2009]. A bigraph [Milner, 2009] is a form of layered graph that superimposes a spatial place graph of locations and a link graph designating communication structure on a single set of vertices. Bigraphs provide models of distributed systems and have been used to generalize process models like petri nets and the π -calculus. Similar ideas have also been used to give layered models of biological systems [Maus et al., 2011].

In the present work, we give a logical analysis of the decomposition of such systems into layers, using concepts similar to ones explored with *bunched logics*; that is, logics that freely combine logical systems of different structural strengths. For example, the logic of bunched implications (BI) [O'Hearn and Pym, 1999; Pym *et al.*, 2004; Galmiche *et al.*, 2005] combines intuitionistic propositional logic [Bezhanishvili and de Jongh, 2006] with multiplicative intuitionistic linear logic [Girard, 1987]. This results in multiple coexisting conjunctions and implications with different logical properties. In particular, in BI we have both the standard conjunction ∧ and the multiplicative conjunction *.

This connective can be understood through an interpretation known as *resource semantics*. Consider a set of resources Res (ranged over by r) that is equipped with an order \sqsubseteq and a commutative and associative operation $\circ : \mathrm{Res}^2 \to \mathrm{Res}$. We think of \sqsubseteq as a way of *comparing* resources and \circ as a way of *composing* resources. The conjunction * is then understood with the semantic clause

 $r \vDash \varphi * \psi$ iff there exists r_1, r_2 s.t. $r_1 \circ r_2 \sqsubseteq r, r_1 \vDash \varphi$ and $r_2 \vDash \psi$

which is read as ' $\varphi * \psi$ holds of resource r iff it is possible to decompose part of r into disjoint resources r_1 and r_2 such that φ holds of r_1 and ψ holds of r_2 '.

Building on this idea, we give a bunched logic suitable for reasoning about the separation of directed graphs into layers. Because of the structural properties of this decomposition we must additionally drop commutativity and associativity from the multiplicative conjunction to correctly capture it. Our work is related to a prior logic for layered graphs, LGL [Collinson *et al.*, 2014; Collinson *et al.*, 2015], with the key difference that our logic extends *intuitionistic* propositional logic rather than classical. As a consequence, we are able to prove completeness for layered graphs (rather than just for more abstract algebras) with respect to a labelled tableaux proof system, a result that (the classical) LGL lacks.

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2 Layered Graphs

We first give a graph-theoretic account of the notion of layering that captures the concept as used in complex systems. Informally, two layers in a directed graph are connected by a specified set of edges, each element of which starts in the upper layer and ends in the lower layer. Our definition contrasts with prior accounts in which the layering structure is left implicit [Fiat *et al.*, 1998; Papadimitriou and Yannakakis, 1991], and generalizes others which consider only a restricted class of layered graphs [Paz, 2011].

We begin by fixing notation and terminology. Given a directed graph, \mathcal{G} , we refer to its *vertex set* by $V(\mathcal{G})$. Its *edge set* is given by a subset $E(\mathcal{G}) \subseteq V(\mathcal{G}) \times V(\mathcal{G})$, while its set of subgraphs is denoted $Sg(\mathcal{G})$, with $H \subseteq \mathcal{G}$ iff $H \in Sg(\mathcal{G})$.

To introduce layers, we identify a distinguished set of edges $\mathcal{E} \subseteq E(\mathcal{G})$. The reachability relation $\leadsto_{\mathcal{E}}$ on subgraphs of \mathcal{G} is then defined $H \leadsto_{\mathcal{E}} K$ iff there exists $u \in V(H)$ and $v \in V(K)$ such that $(u,v) \in \mathcal{E}$. This generates a partial composition $@_{\mathcal{E}}$ on subgraphs of \mathcal{G} . Let \downarrow denote definedness. For subgraphs H and K, $H @_{\mathcal{E}} K \downarrow$ iff $V(H) \cap V(K) = \emptyset$, $H \leadsto_{\mathcal{E}} K$ and $K \not\leadsto_{\mathcal{E}} H$, with output given by the graph union of the two subgraphs and the \mathcal{E} -edges between them. This composition is neither commutative nor (because of definedness) associative.

Figure 1 shows subgraphs H and K for which $H @_{\mathcal{E}} K$ is defined, as well as the resulting composition. We say G is a layered graph (with respect to \mathcal{E}) if there exist H, K such that $H @_{\mathcal{E}} K \downarrow$ and $G = H @_{\mathcal{E}} K$. If this holds, we say H is layered over K and K is layered under H.

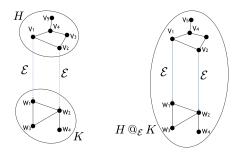


Figure 1: The graph composition $H \otimes_{\mathcal{E}} K$

3 Intuitionistic Layered Graph Logic

Having established the mathematical structures we wish to reason about, we now set up intuitionistic layered graph logic (ILGL). Let Prop be a set of atomic propositions, ranged over by p. The set Form of all propositional formulae is generated by the following grammar:

$$\varphi ::= \mathfrak{p} | \top | \bot | \varphi \wedge \varphi | \varphi \vee \varphi | \varphi \rightarrow \varphi | \varphi \blacktriangleright \varphi | \varphi \blacktriangleright \varphi | \varphi \blacktriangleright \varphi$$

The familiar connectives are interpreted as in intuitionistic propositional logic. The non-commutative and non-associative conjunction \blacktriangleright (intended to capture layering) and its associated left and right implications \blacktriangleright and \blacktriangleright (cf. [Lambek, 1993]) are governed by the proof rules of Figure 2. Intuitionistic negation is defined by $\neg \varphi := \varphi \to \bot$.

$$\frac{\varphi \vdash \psi \qquad \chi \vdash \upsilon}{\varphi \blacktriangleright \chi \vdash \psi \blacktriangleright \upsilon} (\blacktriangleright)$$

$$\frac{\varphi \vdash \psi \blacktriangleright \chi \qquad \upsilon \vdash \psi}{\varphi \blacktriangleright \upsilon \vdash \chi} (\blacktriangleright_1) \qquad \frac{\varphi \blacktriangleright \psi \vdash \chi}{\varphi \vdash \psi \blacktriangleright \chi} (\blacktriangleright_2)$$

$$\frac{\varphi \vdash \psi \blacktriangleright \chi \qquad \upsilon \vdash \psi}{\upsilon \blacktriangleright \varphi \vdash \chi} (\blacktriangleright_1) \qquad \frac{\varphi \blacktriangleright \psi \vdash \chi}{\psi \vdash \varphi \blacktriangleright \chi} (\blacktriangleright_2)$$

Figure 2: Proof rules for the multiplicative fragment

ILGL is interpreted on directed graphs that have been separated into ordered layers. Formally, an *ordered scaffold* is a structure $\mathcal{X} = (\mathcal{G}, \mathcal{E}, X, \preceq)$ such that

- *G* is a directed graph;
- \bullet $\mathcal E$ is a distinguished set of edges;
- X is a subset of $Sg(\mathcal{G})$ satisfying: if $G = H \otimes_{\mathcal{E}} K$ then $G \in X$ iff $H, K \in X$;
- $\bullet \leq$ is an order on X that is reflexive and transitive.

We consider structures that are ordered so we can extend Kripke's ordered possible world semantics of intuitionistic propositional logic [Kripke, 1965]. In Kripke's semantics, truth is *persistent* with respect to the order on possible worlds: if φ is true at a possible world x and $x \preccurlyeq y$ then φ is true at the world y. One can thus think of the intuitionistically valid propositions as those whose truth persists with the introduction of any new fact. In our setting, this means ILGL is suitable for reasoning about properties of graphs that are, for example, inherited from subgraphs, as well as modelling situations in which the components of the system carry a natural order.

A layered graph model $\mathcal{M}=(\mathcal{X},\mathcal{V})$ is given by an ordered scaffold \mathcal{X} and a valuation $\mathcal{V}:\operatorname{Prop}\to\mathcal{P}(X)$ satisfying $G\in\mathcal{V}(p)$ and $G\preccurlyeq H$ implies $H\in\mathcal{V}(p)$. For a layered graph model \mathcal{M} , the satisfaction relation $\vDash_{\mathcal{M}}\subseteq X\times\operatorname{Form}$ is inductively defined in Fig 3. φ is valid for a layered graph model \mathcal{M} if, for all $G\in X$, $G\vDash_{\mathcal{M}}\varphi$. φ is valid if it is valid for all layered graph models \mathcal{M} .

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G \vDash_{\mathcal{M}} \top
                                                      always
            G \vDash_{\mathcal{M}} \bot
                                                     never
             G \vDash_{\mathcal{M}} p
                                        iff
                                                     G \in \mathcal{V}(p)
  G \vDash_{\mathcal{M}} \varphi \wedge \psi
                                                     G \vDash_{\mathcal{M}} \varphi and G \vDash_{\mathcal{M}} \psi
  G \vDash_{\mathcal{M}} \varphi \lor \psi
                                         iff
                                                     G \vDash_{\mathcal{M}} \varphi \text{ or } G \vDash_{\mathcal{M}} \psi
                                                     for all G \preccurlyeq H, H \vDash_{\mathcal{M}} \varphi implies H \vDash_{\mathcal{M}} \psi
G \vDash_{\mathcal{M}} \varphi \to \psi
                                         iff
 G \vDash_{\mathcal{M}} \varphi \blacktriangleright \psi
                                                     there exist H, K s.t. H @_{\mathcal{E}} K \leq G
                                                      and H \vDash_{\mathcal{M}} \varphi and K \vDash_{\mathcal{M}} \psi
                                                     for all H, K : G \preccurlyeq H, H @_{\mathcal{E}} K \downarrow and
G \vDash_{\mathcal{M}} \varphi \rightarrow \psi
                                                      H \vDash_{\mathcal{M}} \varphi \text{ implies } H @_{\mathcal{E}} K \vDash_{\mathcal{M}} \psi
                                                     for all H, K : G \preceq H, K @_{\mathcal{E}} H \downarrow and
G \vDash_{\mathcal{M}} \varphi \blacktriangleright \psi
                                                      H \vDash_{\mathcal{M}} \varphi \text{ implies } K @_{\mathcal{E}} H \vDash_{\mathcal{M}} \psi
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Figure 3: Satisfaction on layered graph models for ILGL

Consider the order given by $G \preceq G'$ iff $G' \subseteq G$. This

has a spatial interpretation: the further up the order, the more specific the location. With this order, we can understand the semantic clause for $\varphi \blacktriangleright \psi$ as 'G is contained in a layered graph $H @_{\mathcal{E}} K$ such that H satisfies φ and K satisfies ψ '. Similarly, the clause for $\varphi \blacktriangleright \psi$ states that 'for all subgraphs H of G, if K satisfies φ and is layered under H then the layered graph $H @_{\mathcal{E}} K$ satisfies ψ '. Finally, $\varphi \blacktriangleright \psi$ is the dual of the case for \blacktriangleright , with K instead layered over H.

4 A Labelled Tableaux System for ILGL

Labelled tableaux systems [Fitting, 1972] are proof calculi that have proved extremely useful in the study of bunched logics. We give a labelled tableaux system for ILGL in the style pioneered on tableaux systems for the bunched logics BBI and DMBI [Larchey-Wendling, 2014; Courtault and Galmiche, 2015] and in the spirit of previous work for BI [Galmiche *et al.*, 2005].

The proof system centres around expressions of the form $\mathbb{S}\varphi: x$, where $\mathbb{S}\in\{\mathbb{T},\mathbb{F}\}$ is a sign (denoting true or false), φ is a formula of ILGL, and x is a syntactic object called a label. The set of all labels \mathbb{L} is inductively generated from a set of atomic labels $(c_i)_{i\in\mathbb{N}}$ and a concatenation operation. We call expressions of the form $\mathbb{S}\varphi: x$ labelled formulae. We additionally define syntactic expressions $x \preccurlyeq y$ (where x and y are labels) called constraints. Tableaux are then tree-structured derivations with labelled formulae at each node and a set of constraints associated with each branch.

The system is specified by a set of tableau expansion rules, a selection of which are given in Figure 4. The premiss of each rule gives a condition a branch must satisfy to allow the rule to be applied to it. Here $\mathcal F$ refers to the labelled formulae on the branch and $\overline{\mathcal C}$ refers to the branch's associated set of constraints. The conclusion then shows how the tableau is expanded after rule application: for a conclusion $\langle X,Y\rangle$, the branch is extended by the labelled formulae in X and the constraints in Y are added to the branch's constraint set. In cases where there are multiple conclusions — for example, $\langle \mathbb F | \mathbf F \rangle$ — the branch splits.

$$\frac{\mathbb{F}\varphi \vee \psi : x \in \mathcal{F}}{\langle \{\mathbb{F}\varphi : x, \mathbb{F}\psi : x\}, \emptyset \rangle} \langle \mathbb{F} \vee \rangle}$$

$$\frac{\mathbb{F}\varphi \to \psi : x \in \mathcal{F}}{\langle \{\mathbb{T}\varphi : c_i, \mathbb{F}\psi : c_i\}, \{x \preccurlyeq c_i\} \rangle} \langle \mathbb{F} \to \rangle}$$

$$\frac{\mathbb{F}\varphi \blacktriangleright \psi : x \in \mathcal{F} \text{ and } yz \preccurlyeq x \in \overline{\mathcal{C}}}{\langle \{\mathbb{F}\varphi : y\}, \emptyset \rangle \mid \langle \{\mathbb{F}\psi : z\}, \emptyset \rangle} \langle \mathbb{F} \blacktriangleright \rangle}$$

$$\frac{\mathbb{F}\varphi \blacktriangleright \psi : x \in \mathcal{F}}{\langle \{\mathbb{T}\varphi : c_j, \mathbb{F}\psi : c_jc_i\}, \{x \preccurlyeq c_i, c_jc_i \preccurlyeq c_jc_i\} \rangle} \langle \mathbb{F} \blacktriangleright \rangle}$$
with c_i and c_j being fresh atomic labels

Figure 4: Some tableaux rules for ILGL

Tableaux for a formula φ are defined inductively. First, the singleton tableau $[\mathbb{F}\varphi:c_0]$ consisting of the single node $\mathbb{F}\varphi:c_0$ is a tableau for φ . Given a tableau \mathcal{T} for φ , if a

branch satisfies the condition of a proof rule $\langle \mathbb{S} \circ \rangle$, the tableau \mathcal{T}' that results from the application of $\langle \mathbb{S} \circ \rangle$ is a tableau for φ . A branch of a tableau is considered inconsistent if one of a set of predefined *closure conditions* is satisifed. For example, if both $\mathbb{T}\varphi: x$ and $\mathbb{F}\varphi: x$ occur on the branch. We say such a branch is *closed*. If all the branches of a tableau are closed, we call it a *closed tableau*. A *tableau proof of* φ in the labelled tableaux system is a finite closed tableau for φ .

This can most easily be understood through an example. Figure 5 shows a tableau proof of the formula $q \blacktriangleright (q \blacktriangleright (p \rightarrow (p \lor q)))$. We begin by placing the formula at the root of the tree, labelled with sign $\mathbb F$ and c_0 .

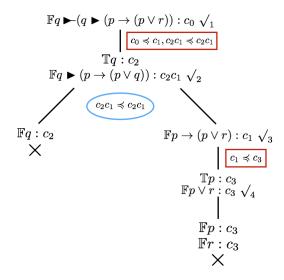


Figure 5: A tableau proof of $q \blacktriangleright (q \blacktriangleright (p \rightarrow (p \lor q)))$

At $\sqrt{\ }_1$, we can apply rule $\langle \mathbb{F} \blacktriangleright \rangle$ as \blacktriangleright is the outermost connective of the formula. This introduces the labelled formulae $\mathbb{T}q:c_2, \mathbb{F}q \blacktriangleright (p \to (p \lor q)):c_2c_1$ and adds the constraints $c_0 \preccurlyeq c_1, c_2c_1 \preccurlyeq c_2c_1$ to the branch. We next apply $\langle \mathbb{F} \blacktriangleright \rangle$ at $\sqrt{\ }_2$. We are able to do so because we have the constraint $c_2c_1 \preccurlyeq c_2c_1$ attached to the branch. This results in the branch splitting: on the left-hand side we have a closed branch because $\mathbb{T}q:c_2$ and $\mathbb{F}q:c_2$ both occur; on the right-hand side we have $\mathbb{F}p \to (p \lor r):c_1$. We can thus apply $\langle \mathbb{F} \to \rangle$, adding the constraint $c_1 \preccurlyeq c_3$ and the labelled formulae $\mathbb{T}p:c_3$ and $\mathbb{F}p\lor r:c_3$. Lastly, we apply $\langle \mathbb{F}\lor \rangle$ at $\sqrt{\ }_4$, introducing $\mathbb{F}p:c_3$. This closes the branch, and with it the tableau, proving $q \blacktriangleright (q \blacktriangleright (p \to (p \lor q)))$.

The labelled tableaux system for ILGL satisifies a special countermodel property: for all formulae $\varphi \in \text{Form}$, if no tableau proof exists for φ , then there exists a tableau with a branch that can be transformed into a layered graph model \mathcal{M} with a subgraph G with the property $G \not\models_{\mathcal{M}} \varphi$. This is achieved by carefully specifying the permitted set of labels and the way new labels and constraints can be introduced by the tableaux rules. We then exhaustively expand the singleton tableau $[\mathbb{F}\varphi:c_0]$ and obtain a branch in which the labels can be transformed into a directed graph that underpins a layered graph model. Satisfiablility in this model corresponds to the signs of the labelled formulae on the branch: in particular, as

 $\mathbb{F}\varphi$: c_0 occurs on the branch, the subgraph corresponding to c_0 does not satisfy φ . Provability in the tableaux system thus captures validity for layered graph models.

Theorem 1 (Soundness & Completeness) For all formulae $\varphi \in \text{Form: } \varphi$ is valid iff there exists a tableau proof for φ .

5 Examples

We now give some illustrative examples to demonstrate how ILGL can be used for complex systems modelling. To do so, we assume two simple modifications to the set up of Section 3 in order to express basic notions of resource and dynamics.

First, the vertices of graphs are labelled with resources. We denote such a labelling by R, with satisfaction given on a graph together with a labelling, G[R]. This allows us to use propositional formulae to denote the presence or absence of resources on a subgraph.

Second, we assume a set of actions a for each model, each with an associated modality $\langle a \rangle$. Actions modify the resource labelling, with $G[R] \models_{\mathcal{M}} \langle a \rangle \varphi$ iff for some well-formed G[R'] such that $G[R] \stackrel{a}{\to} G[R']$, $G[R'] \models_{\mathcal{M}} \varphi$.

Throughout, we assume the scaffolds are ordered by the following containment ordering on labelled graphs: $G[R] \leq G'[R']$ iff $G' \subseteq G$ and $R \subseteq R'$. Intuitively, moving up the order gives a more precise location and a more complete assignment of resources.

5.1 A transportation network

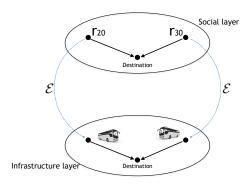


Figure 6: A transportation network

 $\varphi_{meeting}$ assert the existence of a meeting in the social layer, G_1 . Then, if G_2 denotes the graph of the infrastructure layer, we have the formulae

which assert that having two buses available with a total capacity of more than 50 will allow the meeting to proceed, but that a single bus with capacity 40 will not.

5.2 A Security Barrier

This example (see Figure 7) is a situation highlighted by Schneier [Schneier, 2005], wherein a security system is ineffective because of the existence of a side-channel that allows a control to be circumvented.

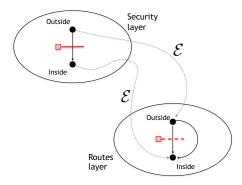


Figure 7: Security barrier with side channel

The security policy, as represented in the security layer, requires that a token be possessed in order to pass from the outside to the inside; that is, $\langle \text{pass} \rangle (\varphi_{\text{in}} \to \varphi_{\text{token}})$. However, in the routes layer it is possible to perform an action $\langle \text{swerve} \rangle$ to drive around the gate. Let G_1 denote the security layer and G_2 denote the routes layer. Then,

$$G_1 @_{\mathcal{E}} G_2 \vDash_{\mathcal{M}} \langle \text{pass} \rangle (\varphi_{\text{in}} \to \varphi_{\text{token}}) \blacktriangleright \langle \text{swerve} \rangle (\varphi_{\text{in}} \land \neg \varphi_{\text{token}})$$

Thus we can express the mismatch between the security policy and the architecture to which it is intended to apply.

6 Conclusions & Further Work

We have specified a bunched logic, ILGL, for reasoning about layered graphs. The logic is sound and complete with respect to a labelled tableaux system that outputs layered graph countermodels for invalid formulae. Through a naive extension with labelled vertices and actions we have demonstrated how the logic can underpin a systems modelling framework.

While layered graphs are a key component of models of complex systems, other structure is also important. For example, in modelling the structure and dynamics of distributed systems it is necessary to capture the architecture of system locations, their associated system resources, and the processes that describe how the system delivers its services. Thus the present work represents only a first step in establishing a logical account of complex systems modelling. A second step would be to reformulate the Hennessy-Milnervan Bentham-style logics of state for location-resource-processes [Collinson and Pym, 2009; Collinson *et al.*, 2012; Anderson and Pym, 2016] to incorporate layering. This would require a significantly more sophisticated notion of resource and dynamics than that given here.

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