

# GEOMETRICAL PROPERTIES OF **SPHERICAL LAGUERRE VORONOI DIAGRAM** WITH APPLICATIONS

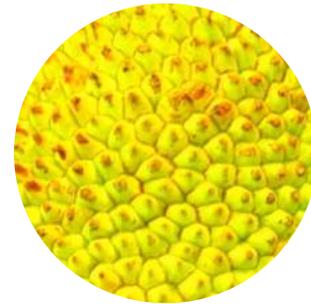
Supanut Chaidee

Department of Mathematics, Faculty of Science  
Chiang Mai University, Thailand

# Motivation



There are many phenomena related to polygonal net problems.



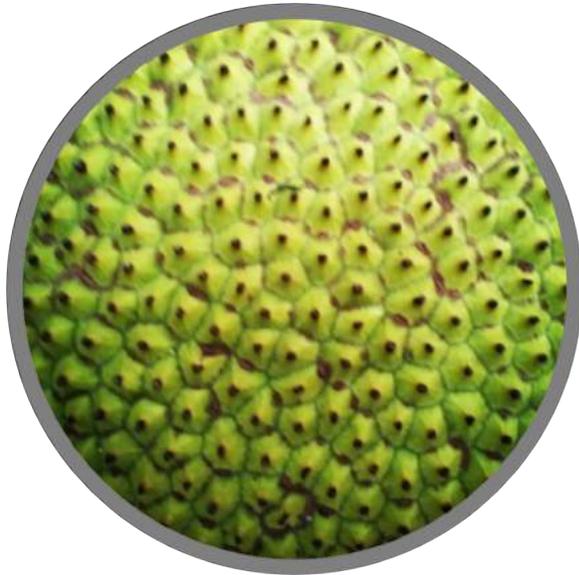
## Patterns on the fruit skins

- Patterns on (approximated) spherical surface



Can we use mathematical concepts to model or understand the pattern formation?

# Tessellation Patterns

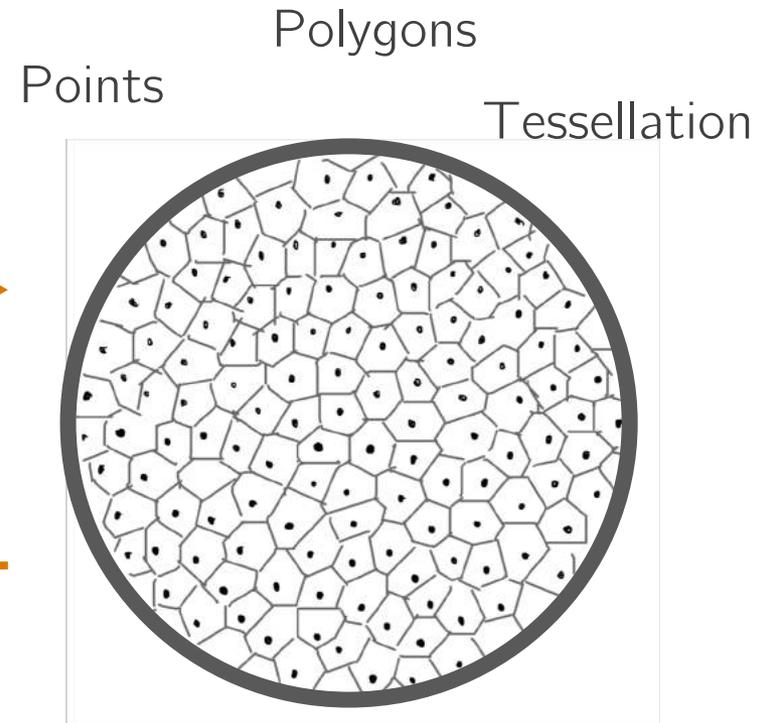


A skin pattern of “Jackfruit”  
*Artocarpus Heterophyllus*

Problem  
Formulation  
→

Geometrical  
Viewpoint

←  
Understanding  
phenomena



## Computational Geometry

*the study of algorithms which can  
be stated in terms of geometry.*

# Voronoi Diagram

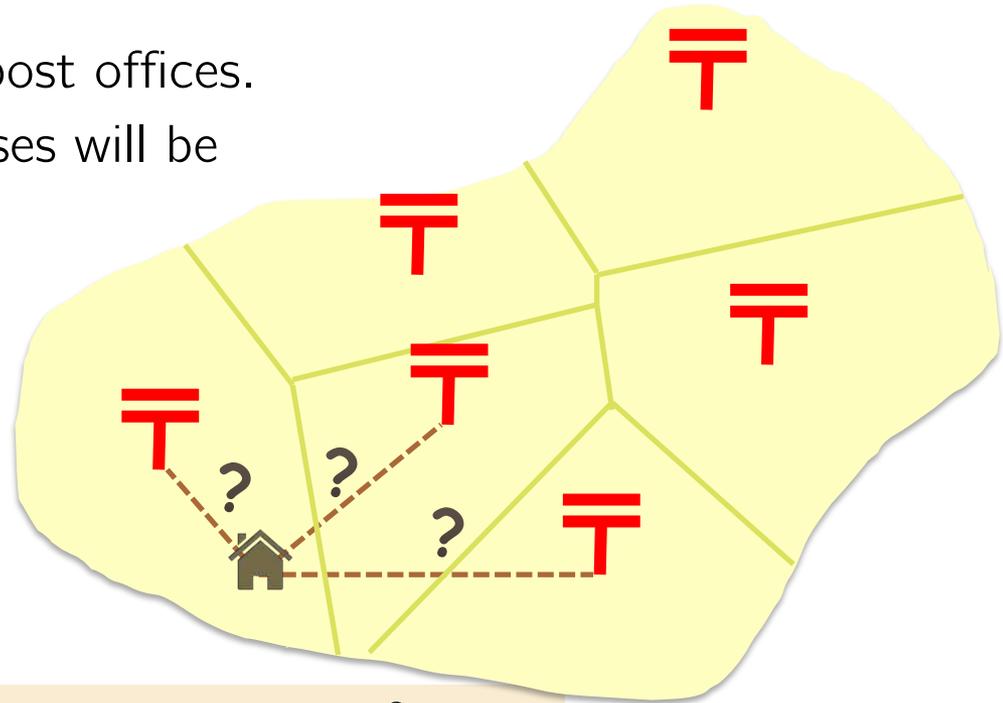
Some problems are related to the space partitioning.

## Post Office Problem

Suppose that a city has a set of post offices.

We need to determine which houses will be operated by which office.

A resident needs to send a letter at a post office near his home!



A subdivision of a plane into these regions is called **Voronoi diagram**.

Let  $P = \{p_1, p_2, \dots, p_n\}$  be a set of  $n$  sites over  $\mathbb{R}^2$ .

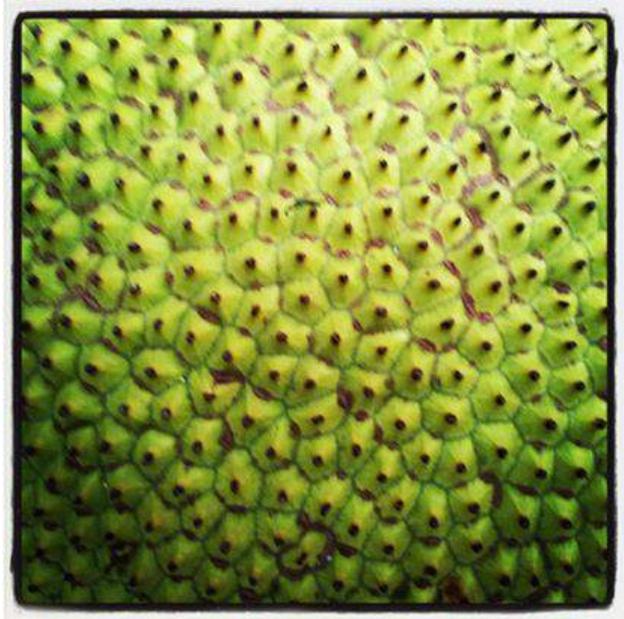
The **Voronoi region**  $V(p_i)$  of the site  $p_i \in S$  is defined by

$$V(p_i) = \{x \in \mathbb{R}^2 \mid d(x, p_i) \leq d(x, p_j) \text{ for } i \neq j\}$$

where  $d(x, y)$  denotes the Euclidean distance between points  $x$  and  $y$  in the plane.

# Considering on the Real-world Problem..

Is ordinary Voronoi diagram enough for modeling the pattern?



Jackfruit skin pattern



Lychee skin pattern

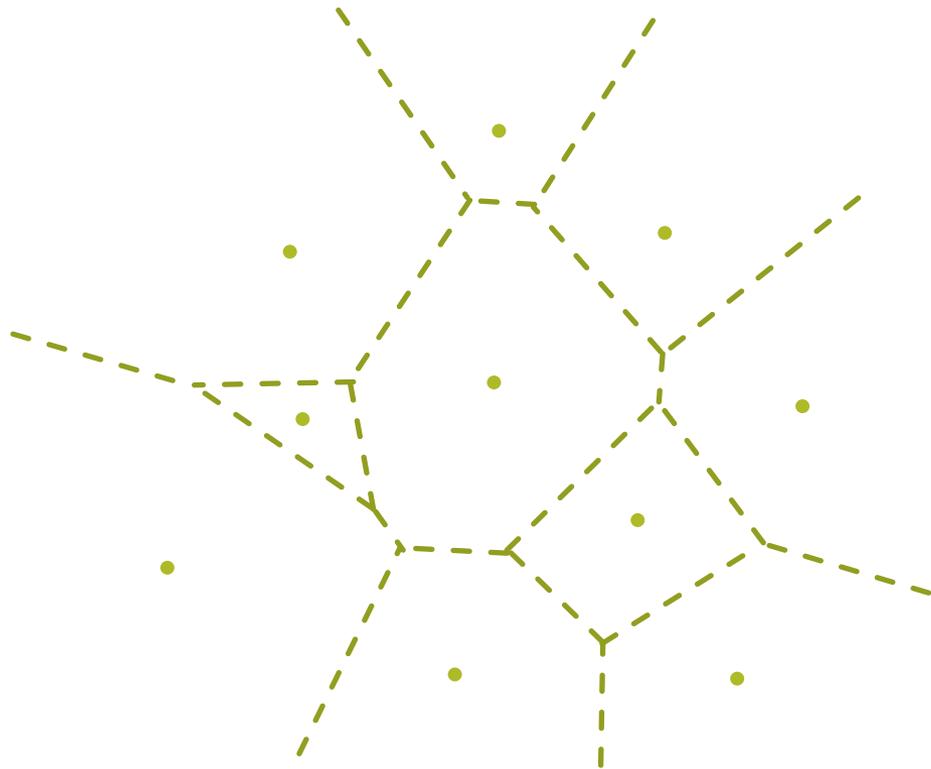


To model this kind of tessellation, **weights** of each generator is important due to real-world phenomena.

# Considering on the Real-world Problem..



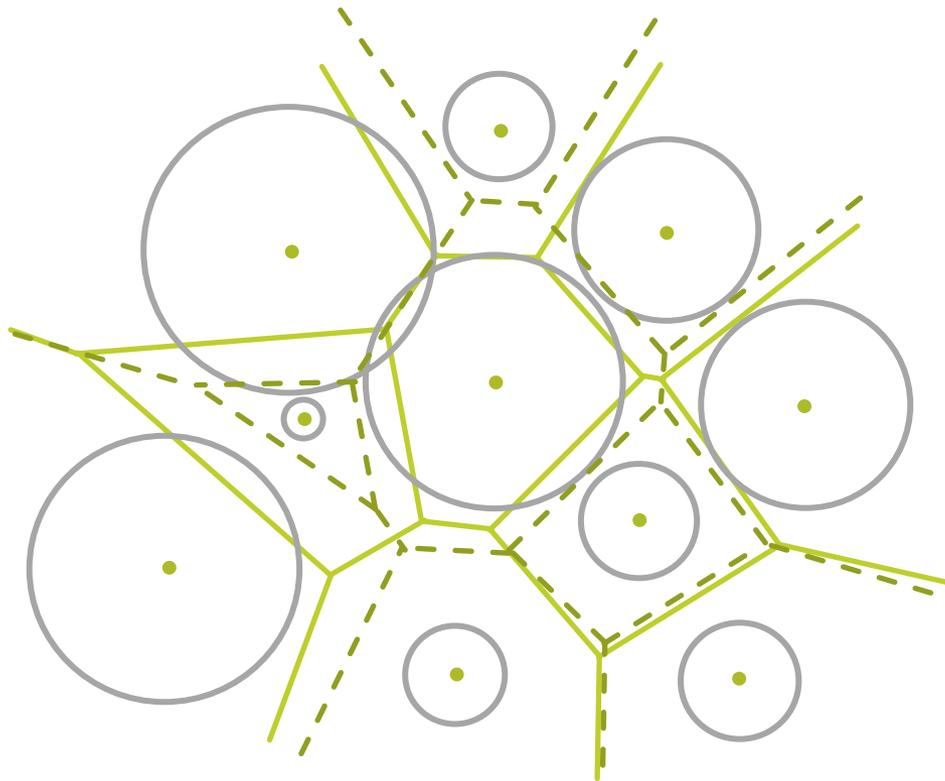
# Voronoi Diagram



Voronoi Diagram

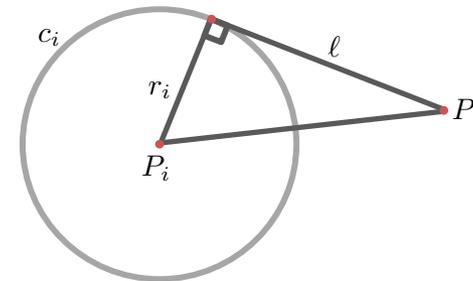
$V(\text{space}/\text{generator}/\text{distance})$

# Voronoi Diagram



Voronoi Diagram

V(space/generator/distance)

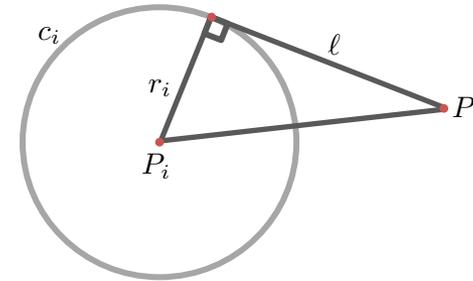


Each generator comes with its circle.

$$d_L(P, c_i) = d(P, P_i)^2 - r_i^2$$

Laguerre Voronoi Diagram

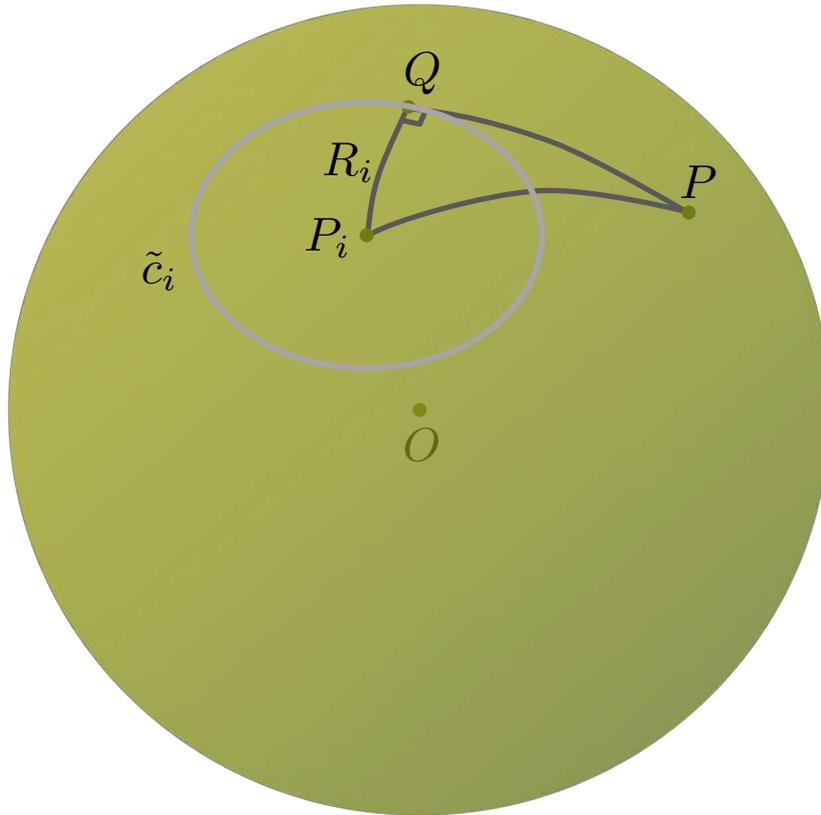
# Voronoi Diagram



Each generator comes with its circle.

$$d_L(P, c_i) = d(P, P_i)^2 - r_i^2$$

Laguerre Voronoi Diagram



A spherical circle on  $U$  corresponding to  $P_i$  is

$$\tilde{c}_i = \{Q \in U \mid \tilde{d}(P_i, Q) = R_i\}$$

where  $0 \leq R_i/R < \pi/2$ .

The Laguerre Proximity

$$\tilde{d}_L(P, \tilde{c}_i) = \frac{\cos(\tilde{d}(P, P_i)/R)}{\cos(R_i/R)}$$

V(sphere/points/Laguerre)

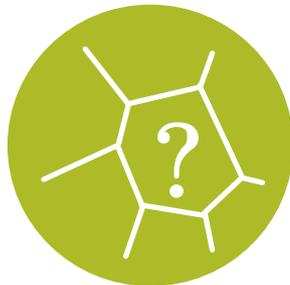
Spherical Laguerre Voronoi Diagram  
(SLVD)

# Research Scopes

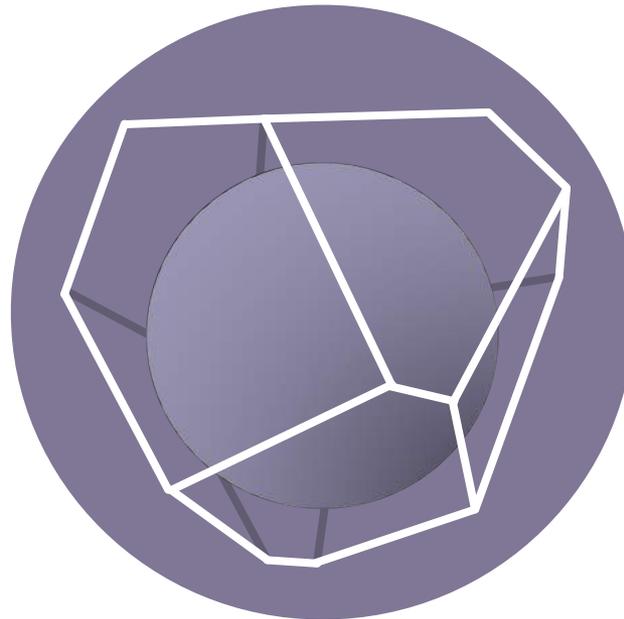


to construct mathematical models for understanding the polygonal tessellation on the fruit skins

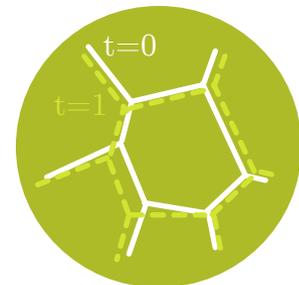
We use the **spherical Laguerre Voronoi diagram** as a main tool for solving the problem.



Inverse Voronoi Diagram Problem

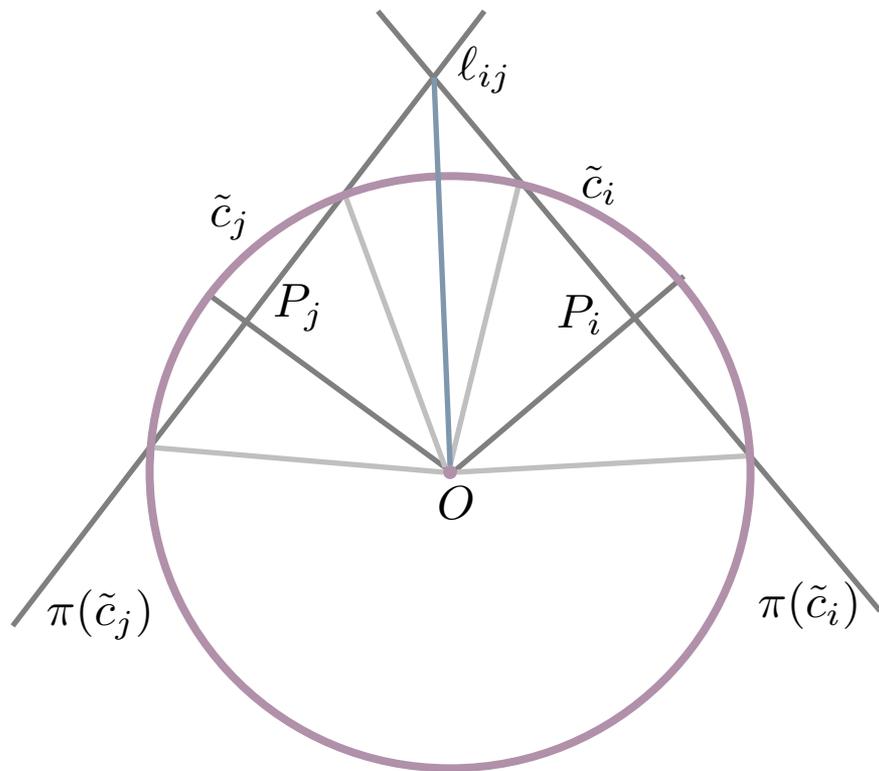


Properties of the **spherical Laguerre Voronoi diagram**

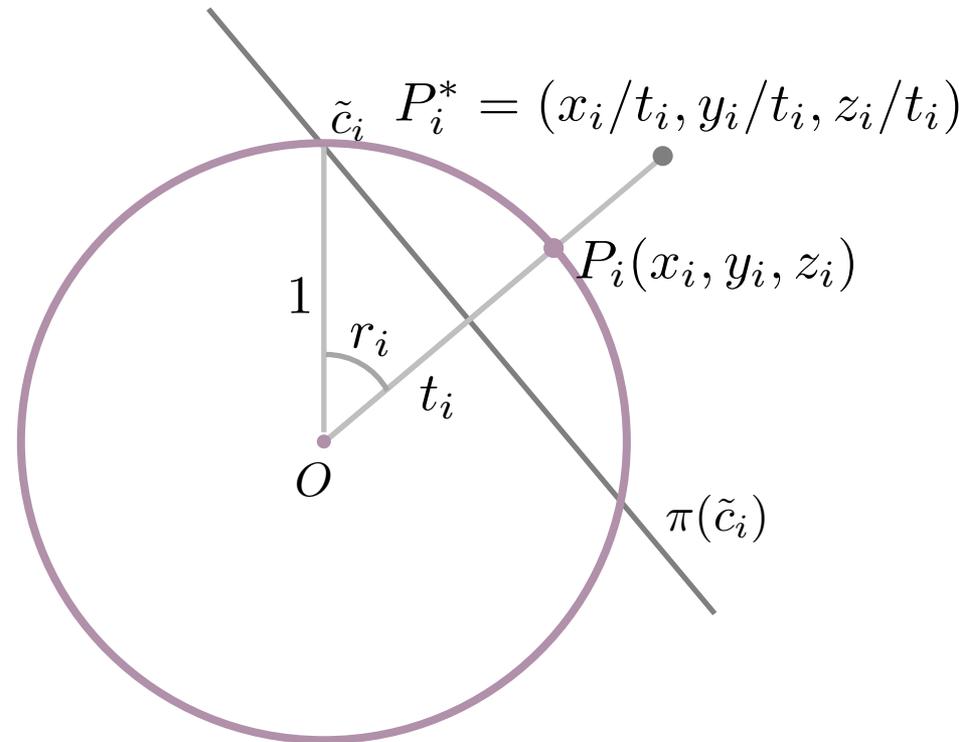


Voronoi-based Modeling

# Construction of SLVD

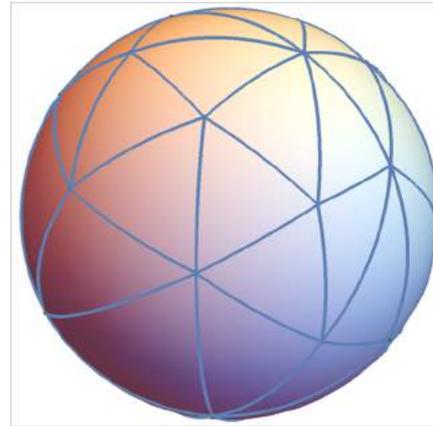


Spherical Laguerre  
Voronoi diagram

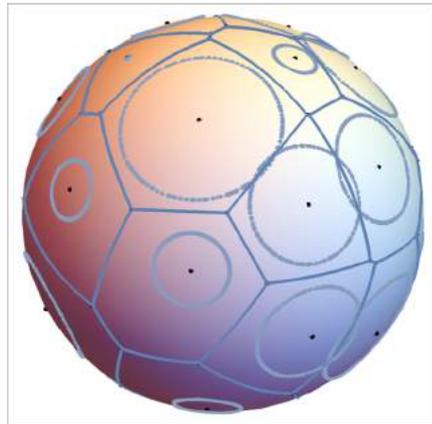


Spherical Laguerre  
Delaunay diagram

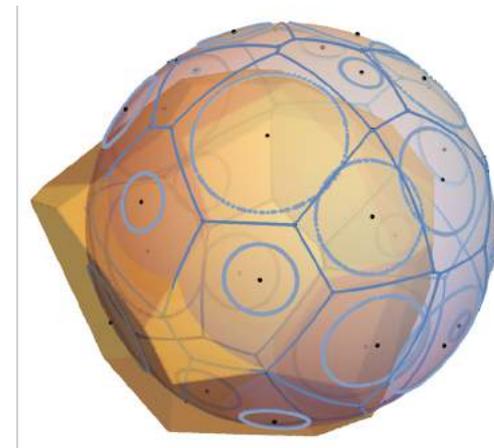
# Corresponding Structures



Spherical Laguerre  
Delaunay Diagram



Spherical Laguerre  
Voronoi diagram



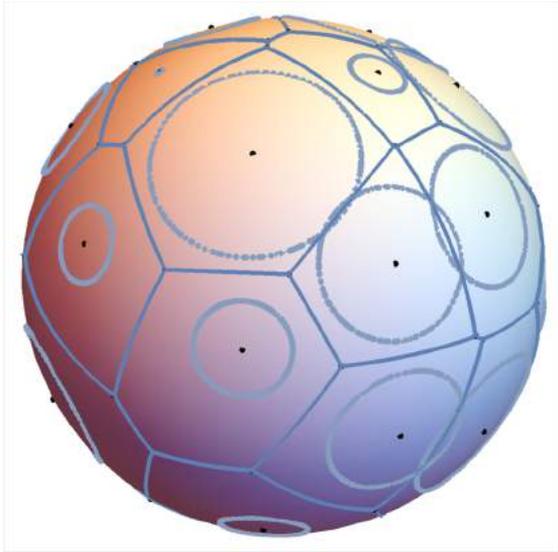
Convex polyhedron

[1] K. Sugihara. Laguerre Voronoi Diagram on the Sphere,  
Journal for Geometry and Graphics, 6:1, 69–81 (2002).

[2] S. Chaidee, K. Sugihara. Recognition of Spherical Laguerre Voronoi Diagram,  
submitted

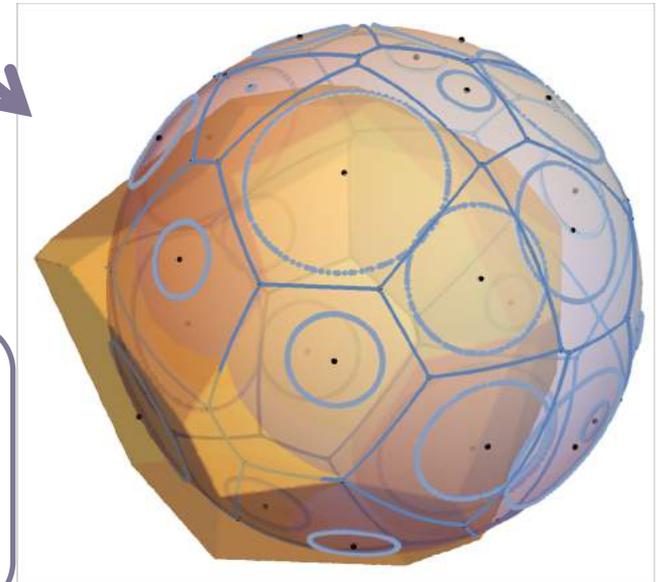


# Correspondence between SLVD and Polyhedra



Spherical Laguerre  
Voronoi diagram

By definition and  
construction algorithms

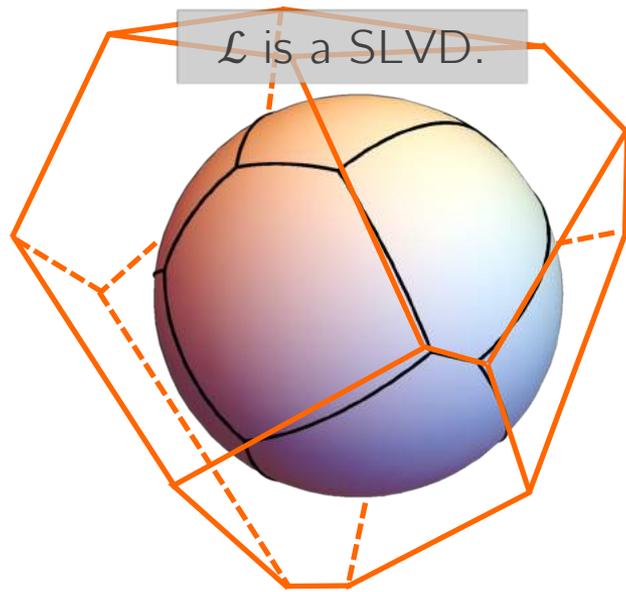


Convex polyhedron

## Proposition

$\mathcal{L}$  is a SLVD if and only if there is a convex polyhedron  $\mathcal{P}$  containing the center of the sphere whose central projection coincides with  $\mathcal{L}$ .

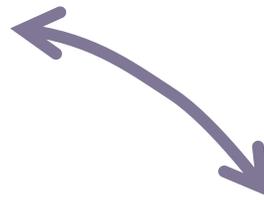
# Correspondence between SLVD and Polyhedra



## Polyhedron transformation

For a point  $\mathbf{v}_a = (t_a, x_a, y_a, z_a) \in P^3(\mathbb{R})$  in the homogeneous coordinate system, define a map  $f : P^3(\mathbb{R}) \rightarrow P^3(\mathbb{R})$  such that

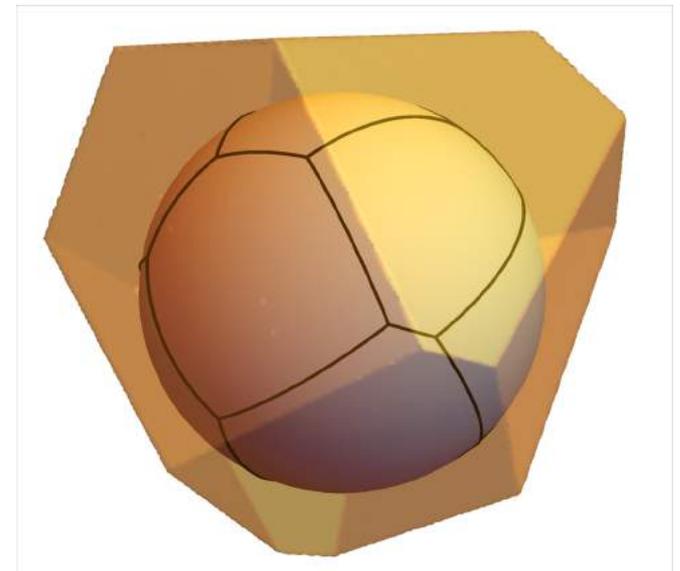
$$f(\mathbf{v}_a) = \begin{pmatrix} \alpha & \beta & \gamma & \delta \\ 0 & \eta & 0 & 0 \\ 0 & 0 & \eta & 0 \\ 0 & 0 & 0 & \eta \end{pmatrix} \mathbf{v}_a$$



### Theorem

There exists a transformation satisfying the projection preservation properties.

We proposed algorithms for constructing a polyhedron with respect to SLVD.



# Tessellation Analysis

inverse  
SLVD

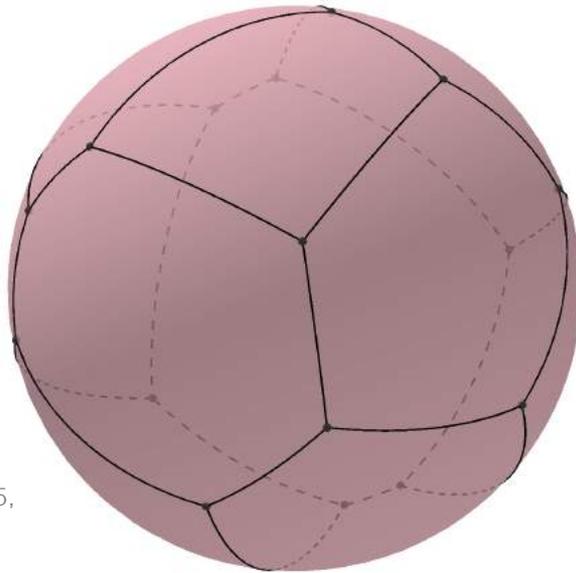
Recognition Problem



find the SLVD which best fits to the given tessellation

Approximation Problem

S. Chaidee and K. Sugihara (2018), *Spherical Laguerre Voronoi Diagram Approximation of Tessellation without Generators*, Graphical Models 95, pp. 1 – 13



recover the generators and their weights.

S. Chaidee and K. Sugihara, *Recognition of the Spherical Laguerre Voronoi Diagram*, preprint.

Convex Spherical Tessellation

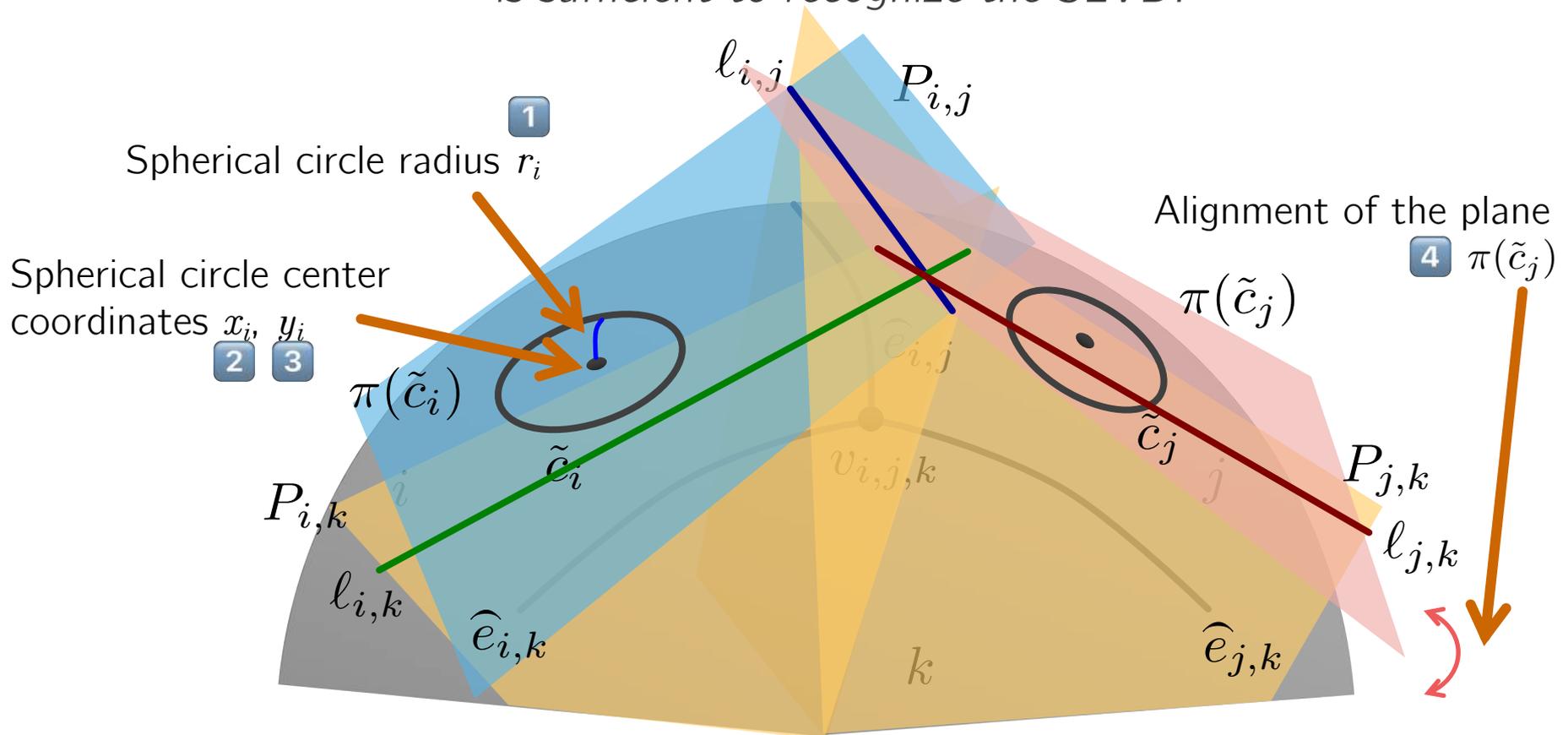
$$\mathcal{T} = \{T_1, \dots, T_n\}$$

# SLVD Recognition Problem

## Theorem

There are exactly four degrees of freedom in the choice of a polyhedron  $\mathcal{P}$  with respect to the given SLVD.

*“Any choice of the initial pair of planes is sufficient to recognize the SLVD.”*



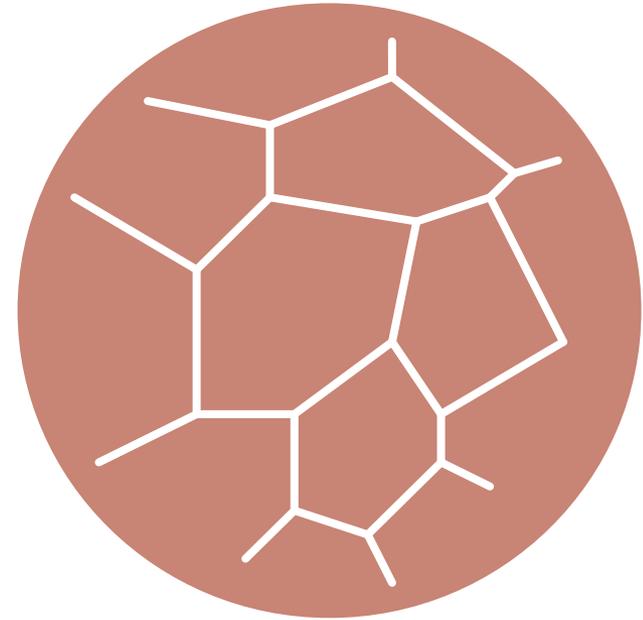
# SLVD Approximation Problem



Voronoi Approximation of  
the Spike-containing Objects

S. Chaidee and K. Sugihara (2017),  
Pattern Analysis and Applications

Approximation of Fruit Skin Patterns Using  
Spherical Voronoi Diagram

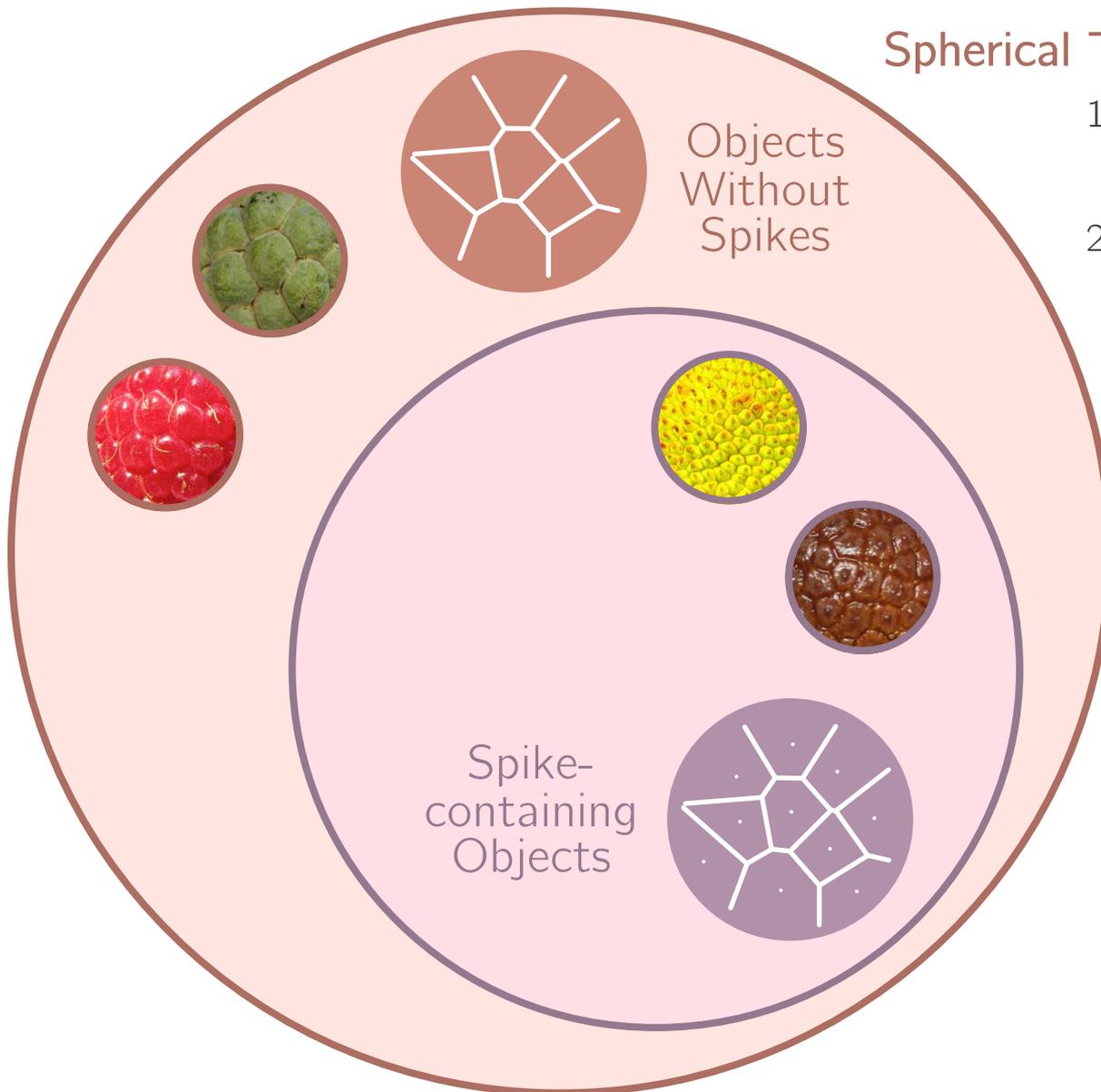


Voronoi Approximation of  
the Objects without Spikes

S. Chaidee, K. Sugihara (2016),  
Discrete and Computational Geometry and Graphs  
(LNCS 9943)

Fitting Spherical Laguerre Voronoi Diagrams  
to Real World Tessellations Using Planar  
Photographic Images

# Object Classification



## Spherical Tessellation Object

1. The object is a convex surface which can be approximated by a sphere.
2. There exists a polygonal net on the surface.

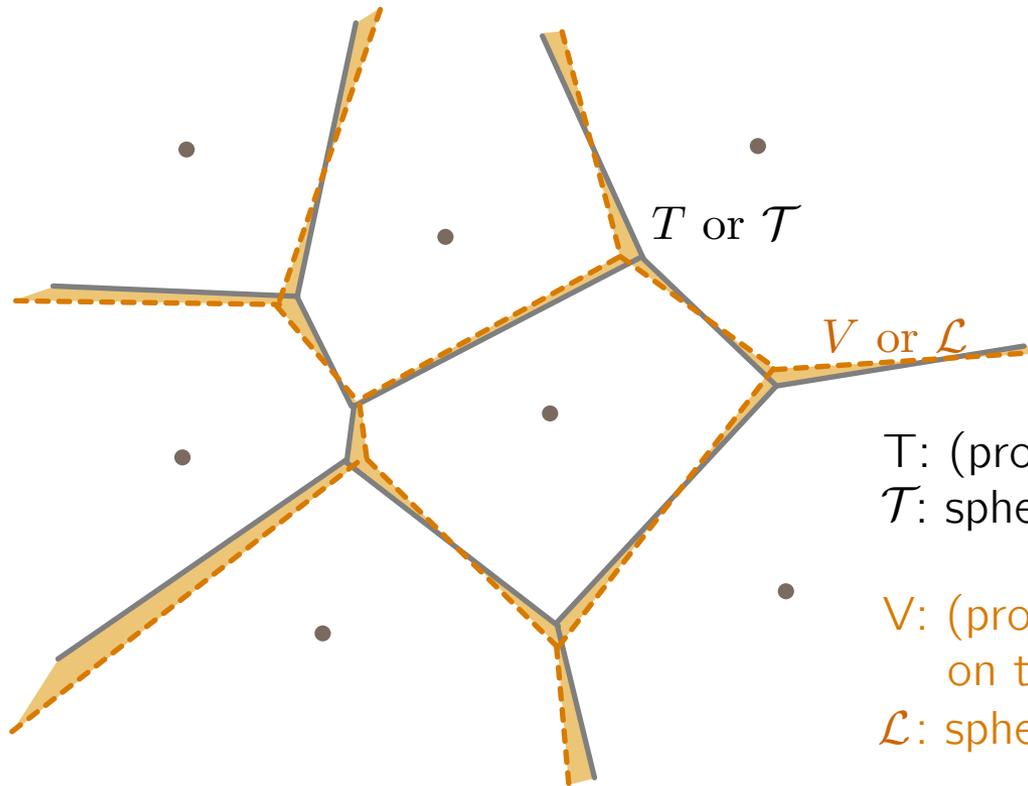
## Spike-containing Object

1. The object is spherical tessellation object.
2. Each unit of the polygonal net contains exactly one spike.
3. The heights of spikes are approximately uniform.

# Voronoi Approximation Problem



Find the spherical (Laguerre) Voronoi diagram which best fits to the given tessellation.



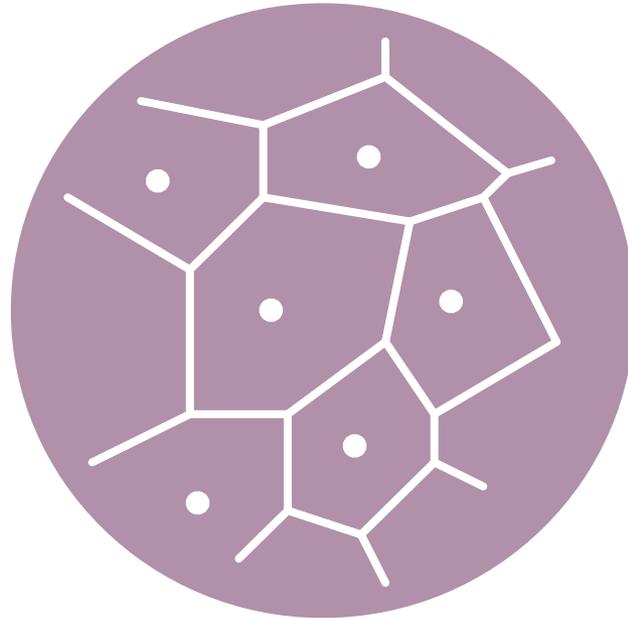
'Discrepancy' is defined as the ratio of sum of different areas to sum of total areas.

$T$ : (projected) tessellation on the plane  
 $\mathcal{T}$ : spherical tessellation on the unit sphere

$V$ : (projected) spherical Voronoi diagram on the plane

$\mathcal{L}$ : spherical Laguerre Voronoi diagram

minimized 'Discrepancy'  $\equiv$  the best fitted Voronoi diagram



Voronoi Approximation of  
the Spike-containing Objects

# Main Framework

Tessellation Fitting using ordinary spherical Voronoi diagram

The discrepancy depends on the sphere radius  $R$ , the spike height  $h$ , and the sphere center position  $(x, z)$ .

The parameters for obtaining the best fit spherical Voronoi diagram

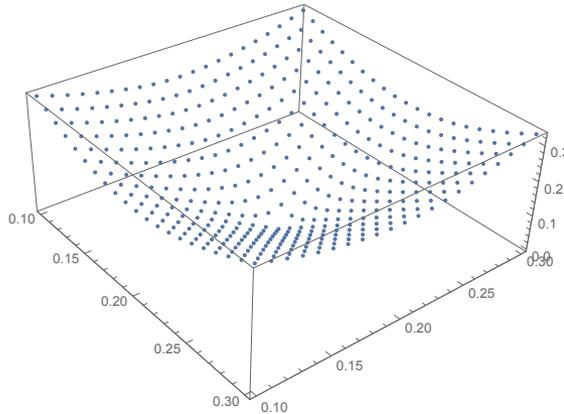
The discrepancy function  $D(x, z, R, h)$  with respect to the variables  $x, z, R, h$



Claim  $\min D(x, z, R, h)$  for obtaining the appropriate  $x, z, R, h$

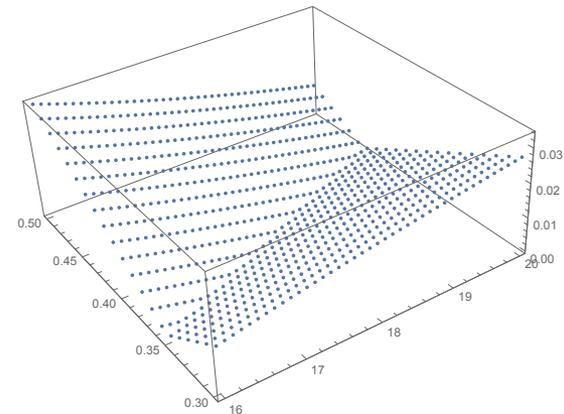
We consider the optimization problem by constructing an iterated (decreasing) sequence tending to the minimum.

Fix  $R, h$  and optimize  $D(x, z)$



The Method of Steepest Descent

Fix  $x, z$  and optimize  $D(R, h)$



The Circular Search

# Weight Approximation

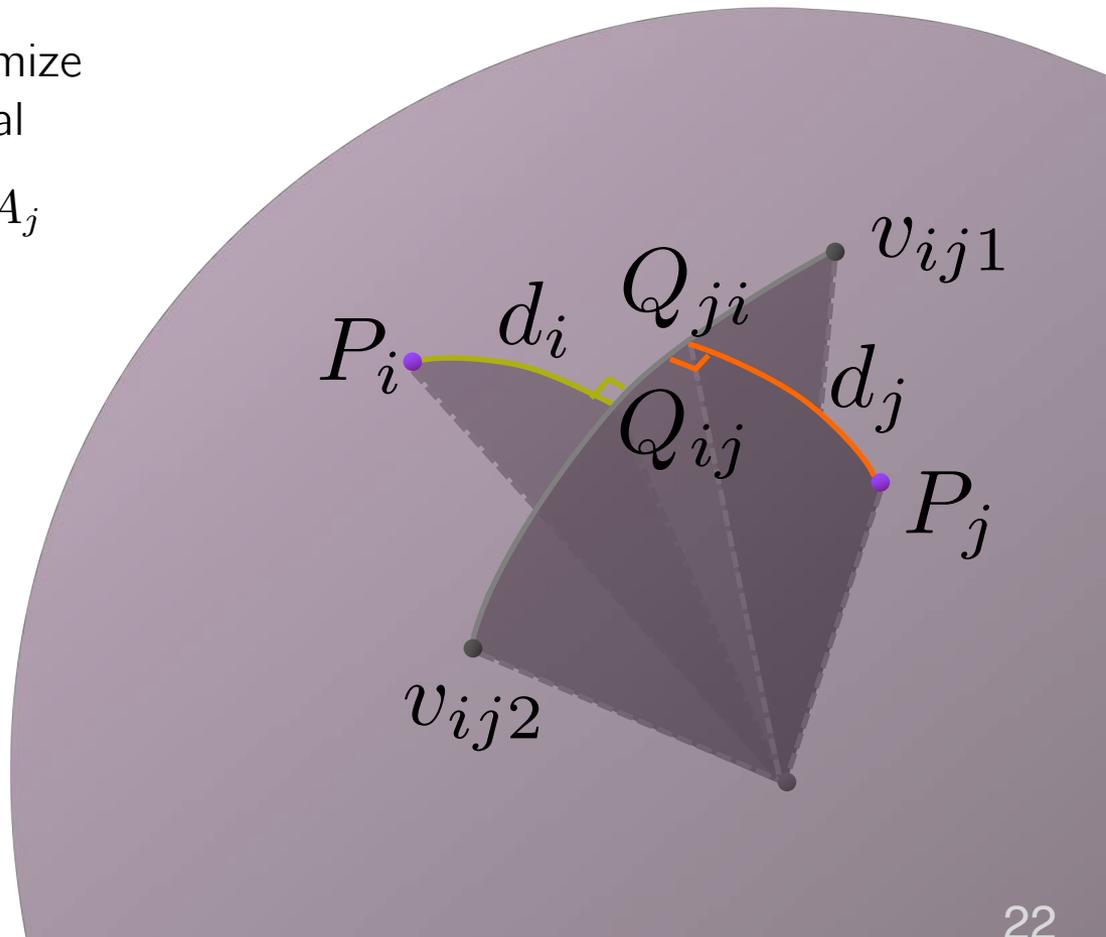
Tessellation Fitting using spherical Laguerre Voronoi diagram

From the fitting result using an ordinary spherical Voronoi diagram, we approximate **weight of each generator**. The tessellation edges of the given tessellation on the plane are projected onto the sphere.

- For each pair, compute that geodesic lengths  $d_i$ ,  $d_j$  and minimize the sum of square of the residual

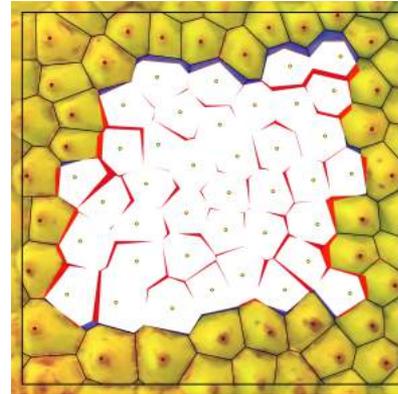
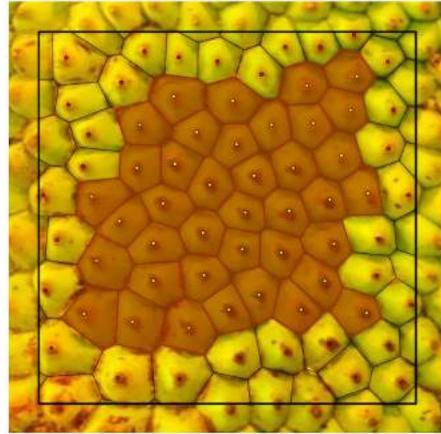
$$\cos\left(\frac{R_j}{R}\right) A_i - \cos\left(\frac{R_i}{R}\right) A_j$$

where  $A_i = \cos\left(\frac{\tilde{d}(P_i, Q_i)}{R}\right)$

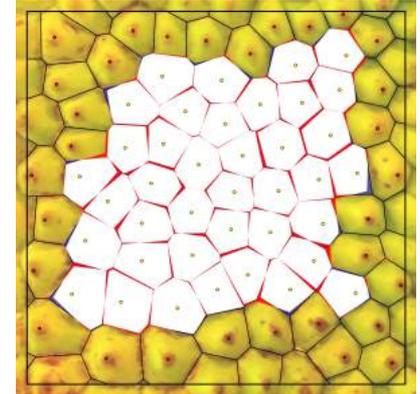


The approximation is done using the fact of SLVD

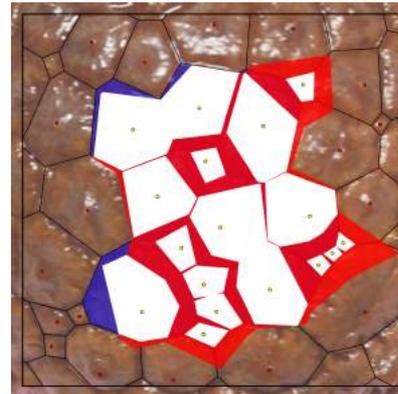
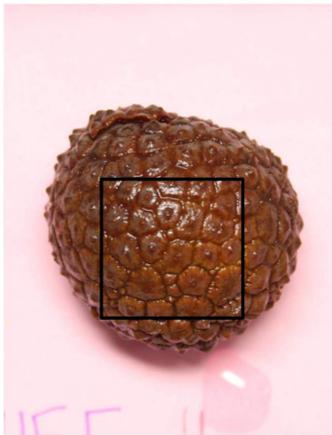
# Experimental Results



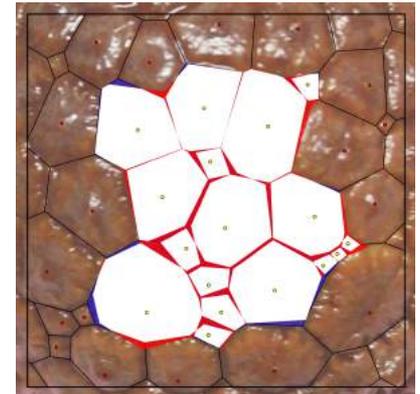
Fitting with the ordinary spherical Voronoi diagram



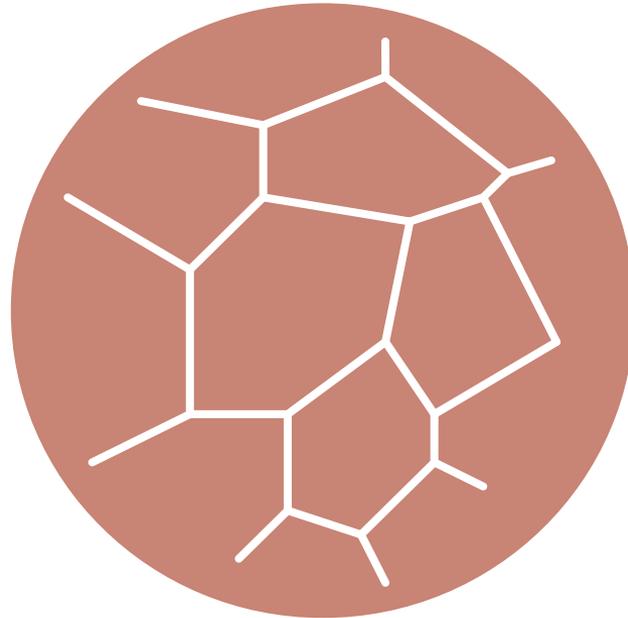
Fitting with the spherical Laguerre Voronoi diagram



Fitting with the ordinary spherical Voronoi diagram



Fitting with the spherical Laguerre Voronoi diagram



Spherical Laguerre Voronoi Diagram  
Approximation Problem  
(Objects without Spikes)

S. Chaidee, K. Sugihara (2018), Graphical Models  
Spherical Laguerre Voronoi Diagram Approximation to Tessellations without Generators

# Tessellation Comparison

Given spherical tessellation  $\mathcal{T}$   
 $\mathcal{T} = \{T_1, \dots, T_n\}$

Suppose that the given tessellation  $\mathcal{T}$  is not SLVD.  
We will find the SLVD that approximates the tessellation  $\mathcal{T}$ .

From **Algorithms**, the polyhedron can be constructed  
**but** the SLVD will not coincide with the given tessellation.



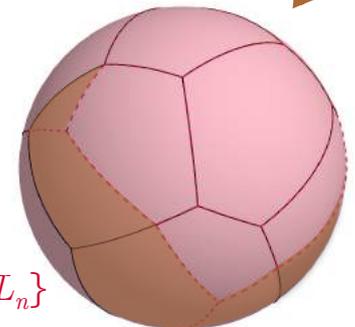
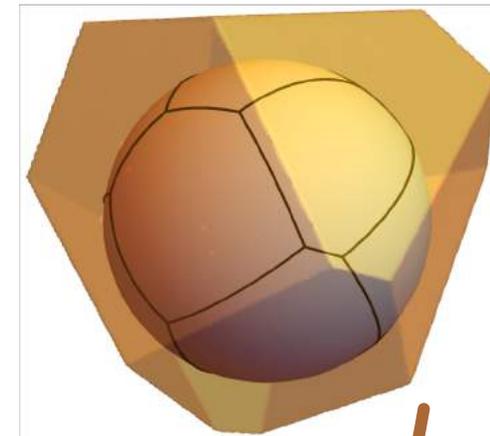
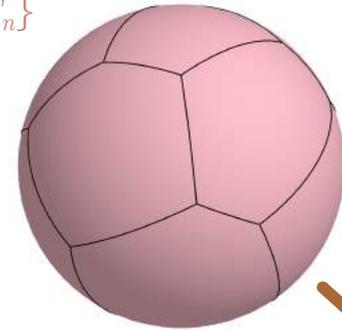
The difference between two tessellations occurs.

## Discrepancy

*The ratio between difference area and total area*

$$\Delta_{\mathcal{T}, \mathcal{L}} = 1 - \frac{1}{4\pi} \sum_{i=1}^n \left( \sum_{j=1}^{m_i} \alpha_{i,j} - (m_i - 2)\pi \right)$$

To find the best fit SLVD, we  
minimize the discrepancy



Difference of  
two tessellations

SLVD  $\mathcal{L}$   
 $\mathcal{L} = \{L_1, \dots, L_n\}$

# Tessellation Fitting

SLVD



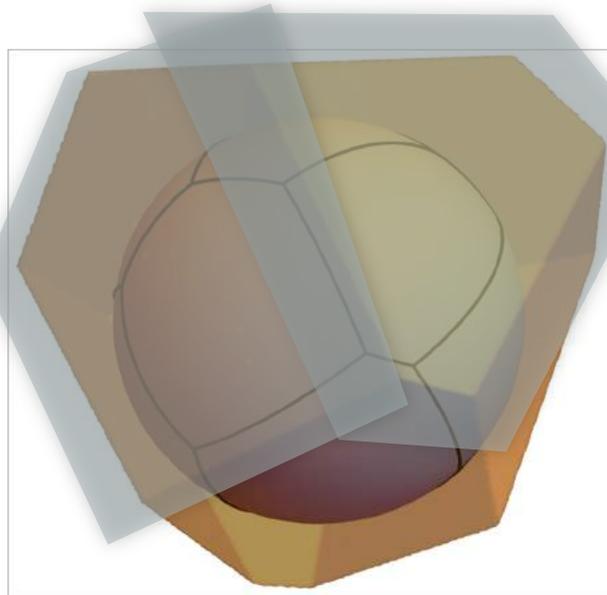
polyhedron



halfspaces



planes



To decrease the discrepancy, we adjust the SLVD.

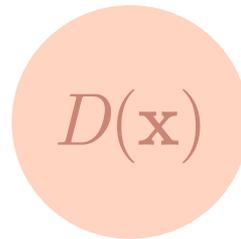
This implies that we adjust the planes.

Plane equation  $P_i: A_i x + B_i y + C_i z = 1$

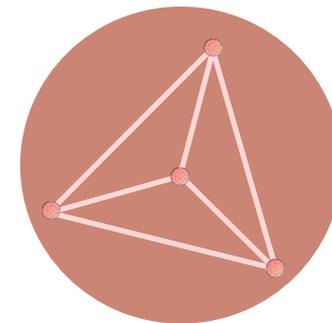
The discrepancy depends on plane parameters  $A_i, B_i, C_i$

For  $n$  tessellation cells, define the discrepancy as a function of  $\mathbf{x} = (A_1, \dots, A_n, B_1, \dots, B_n, C_1, \dots, C_n)$  by

minimize  $D(\mathbf{x}) := \Delta_{\mathcal{T}, \mathcal{L}}$ .



Discrepancy function value  
computed pointwisely

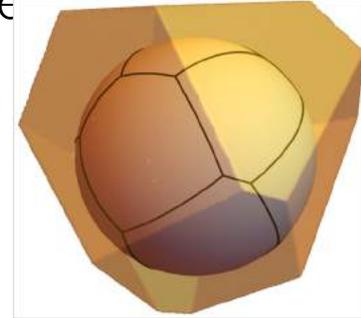


Nelder-Mead Method  
for finding the local minimum

# Interpretation of SLVD

To interpret the meaning of fitted Voronoi diagram, the following goals are preferable

We use **four degrees of freedom Theorem** for adjusting the polyhedron satisfying the real-world desired properties.



Each generator should be **close to the center** of the cell.

- Find the satisfied polyhedron

The generators should **lay inside the cell** as much as possible.

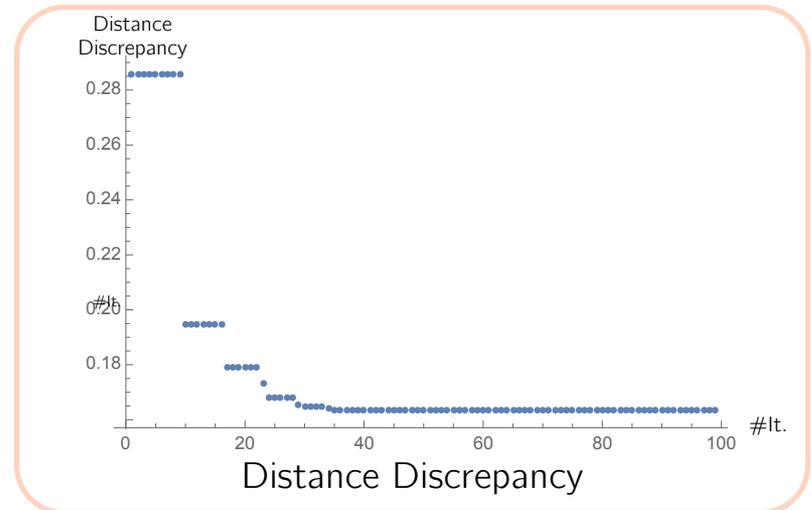
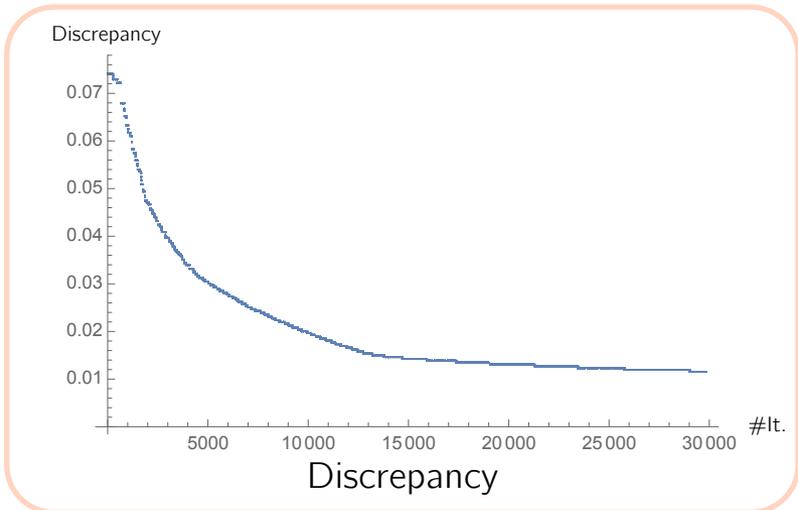
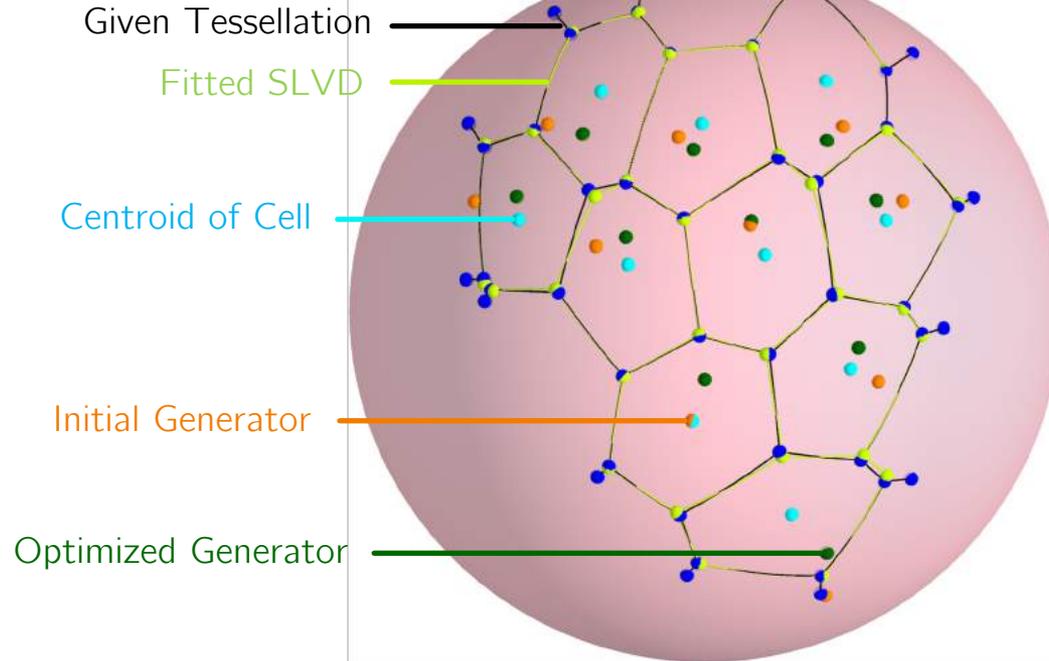
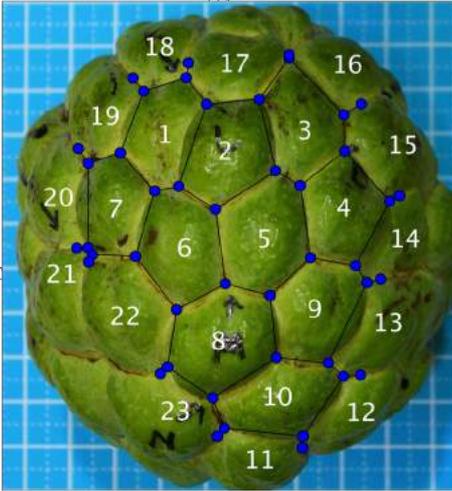
- Expected result from the first goal

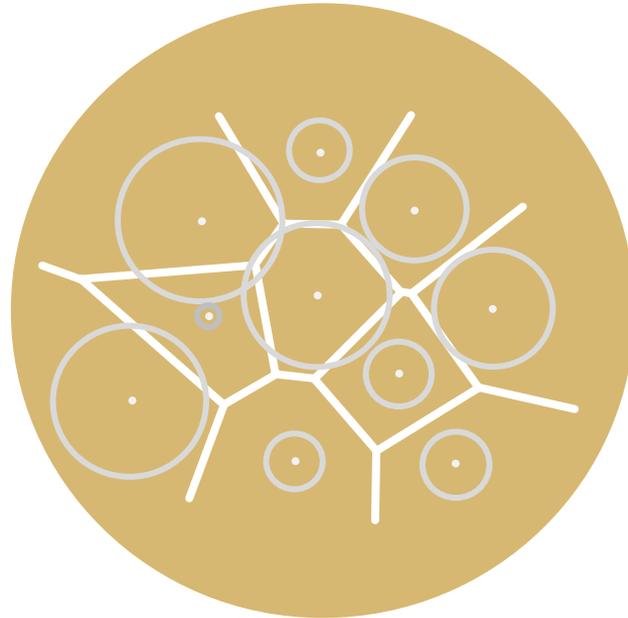
The radii of spherical circles should be a **non-negative number**.

- Shrink the polyhedron until all weights are non-negative

# Experimental Results

Experiments with real data





## Modeling using Spherical Laguerre Voronoi Diagram

S. Chaidee, K. Sugihara, (2019) Graphs and Combinatorics  
Laguerre Voronoi Diagram as a Model for Generating  
the Tessellation Patterns on the Sphere

# Characteristics of Real-World Patterns



Jackfruit  
Multiple fruit



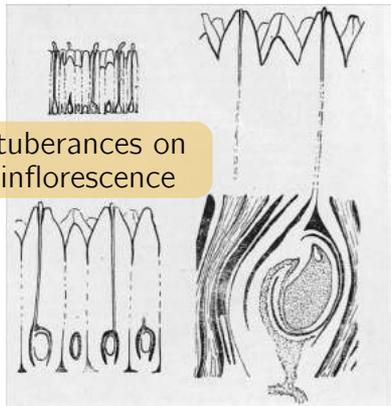
Lychee  
Single fruit



Raspberry  
Aggregate fruit

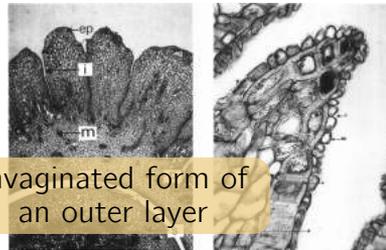


Sugar apple  
Aggregate fruit



Protuberances on an inflorescence

Figure from [21]



Invaginated form of an outer layer

Figure from [94]



Small fruits attach on their flower structure

Figure from [56]

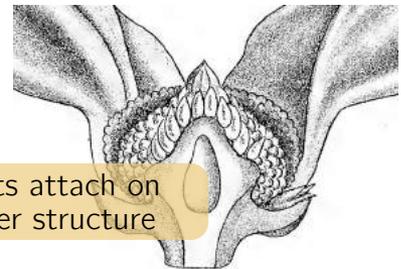
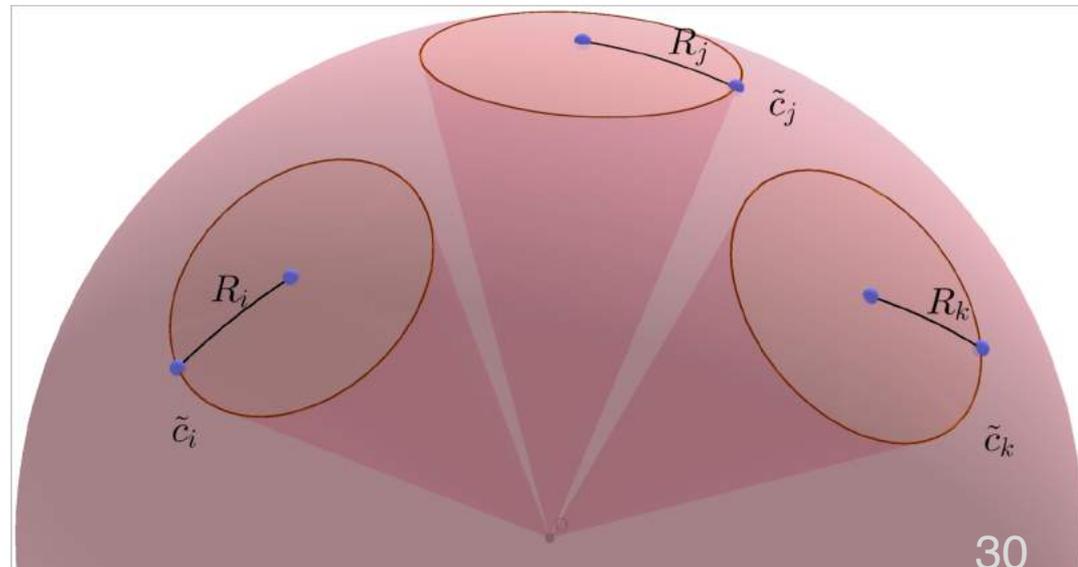


Figure from [43]

- There are microstructures attached on the large object.
- In our model, assume that each unit displays as a **spherical cone** whose base is a spherical circle.
- Microstructures are attached on the **unit sphere**.



# Modeling Assumptions

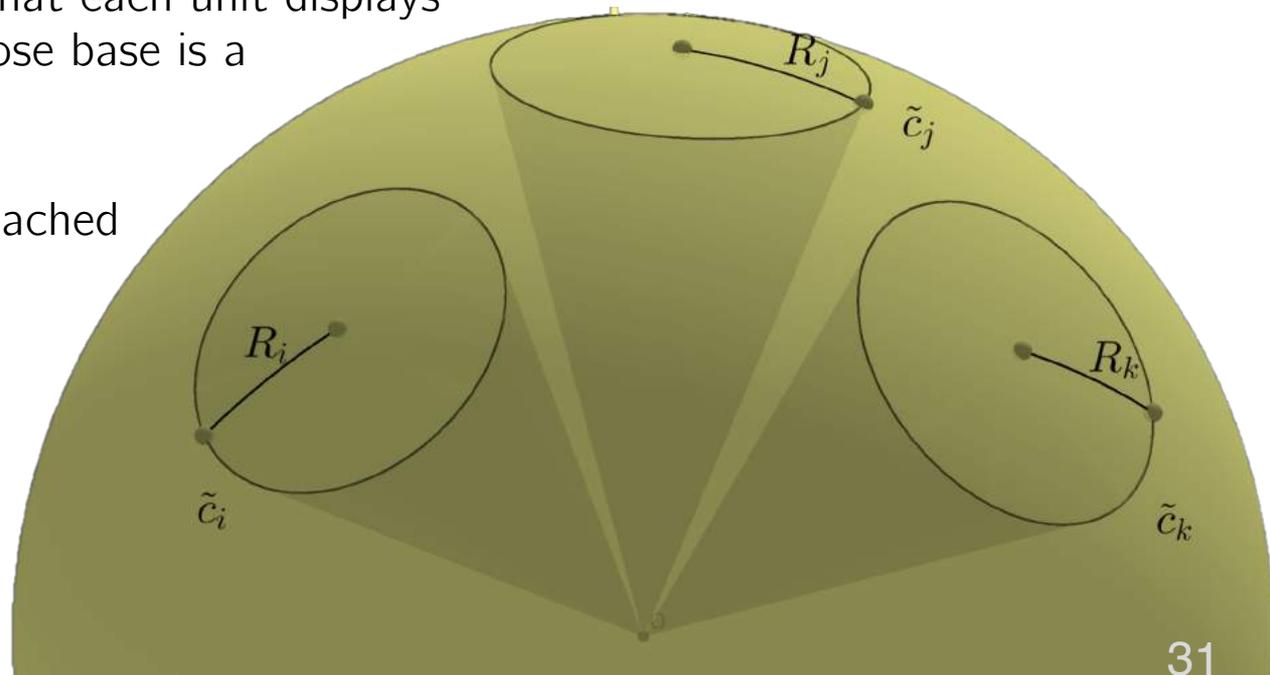
For a unit sphere  $U$ , let  $\mathcal{G}(t) = \{\tilde{c}_1(t), \dots, \tilde{c}_n(t)\}$  be a set of spherical circles at time  $t$  such that

$$\tilde{c}_i(t) = \{p \in U : \tilde{d}(p_i(t), p(t)) = R_i(t)\}.$$

Nondecreasing  
bounded function

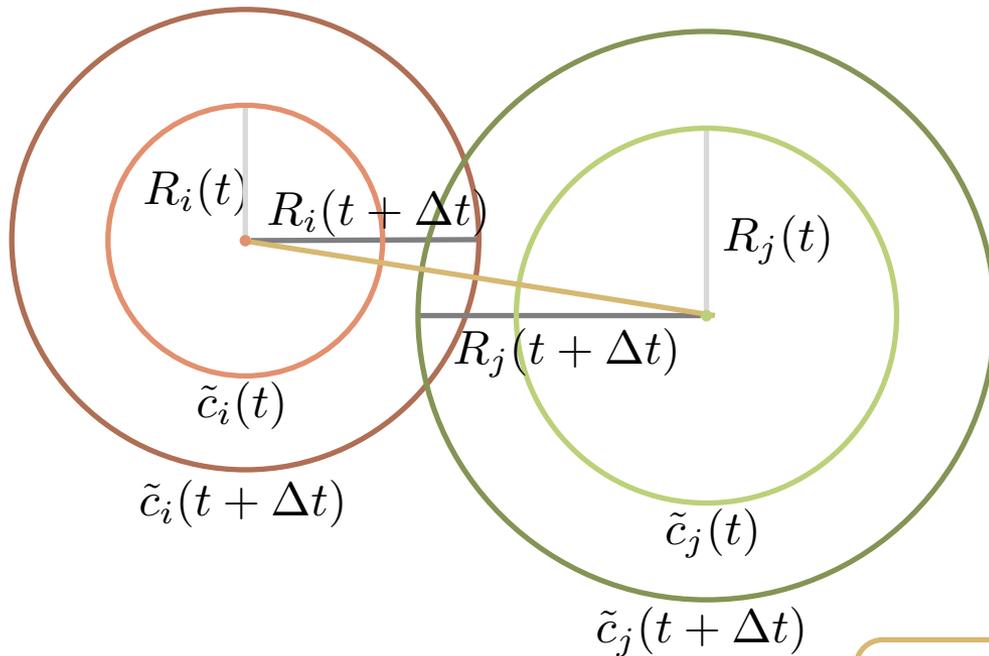
such that  $0 < R_i(t) < \pi/2$ , and  $p_i(t)$  is the spherical circle center at time  $t$ .

- There are microstructures attached on the large object.
- In our model, assume that each unit displays as a **spherical cone** whose base is a spherical circle.
- Microstructures are attached on the **unit sphere**.



# Generator Pushing Model

At time  $t$ , for each corresponding pair  $i, j$  in the spherical Laguerre Delaunay edge of time  $t - 1$ , we consider the dynamical movement of generators.



Define the energy function

$$\Delta E = 0$$

or  $\Delta E = (R_i(t) + R_j(t)) - \tilde{d}(p_i(t), p_j(t))$

$$E(\theta_1^t, \phi_1^t, \dots, \theta_n^t, \phi_n^t) = \sum_{i,j} (\Delta E)^2$$

After two circles touch each other, the circles are moved.

In real world situation, the generating centers are not moved so much.

$$F(\theta_1^t, \phi_1^t, \dots, \theta_n^t, \phi_n^t) = \sum_{i=1}^n (\tilde{d}(p_i(t-1), p(t)))^2$$

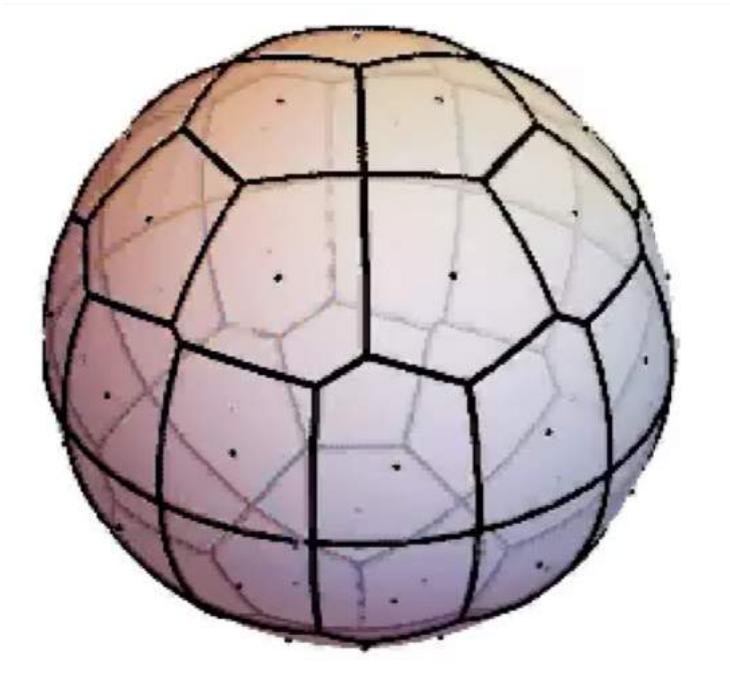
We solve the optimization problem

$$\min\{E(\theta_1^t, \phi_1^t, \dots, \theta_n^t, \phi_n^t), F(\theta_1^t, \phi_1^t, \dots, \theta_n^t, \phi_n^t)\}$$

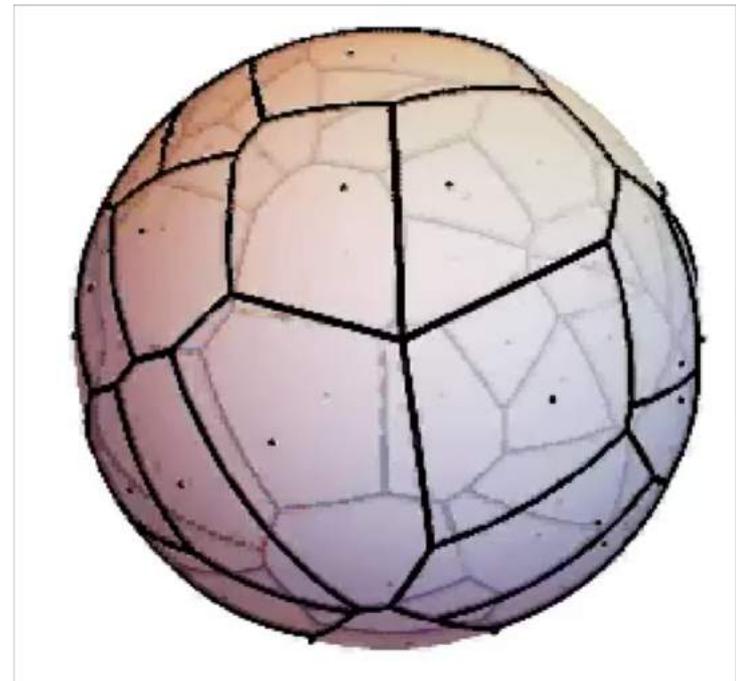
# Simulation

We generate the patterns using the following parameters.

$$n = 50, \omega = 1/8, \epsilon = 10^{-8}, L_i \in \left[ \arccos\left(1 - \frac{1}{n}\right) - \frac{\pi}{36}, \arccos\left(1 - \frac{1}{n}\right) + \frac{\pi}{36} \right]$$
$$k = 0.2, t_0 = 15$$

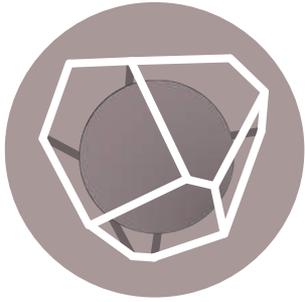


Equidistributed Points

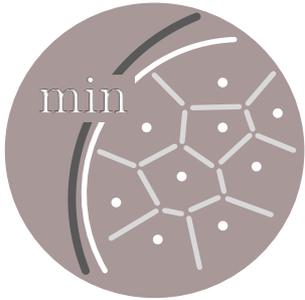


Random Points

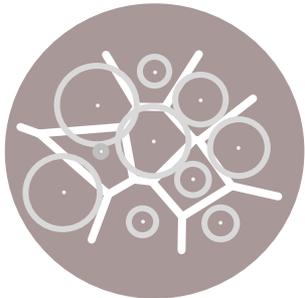
# Concluding Remarks & Future Works



The properties of SLVD based on the polyhedron help us to solve the recognition and approximation problem.



We proposed the models corresponding to the biological information for generating the tessellation pattern on the sphere using SLVD.



The properties of SLVD based on polyhedra may allow us to define the new kind of the Voronoi diagram.

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Prof. Kokichi Sugihara  
Main Supervisor



明治大学 先端数理科学研究科

Graduate School of Advanced Mathematical Sciences, Meiji University



明治大学先端数理科学インスティテュート

Meiji Institute for Advanced Study of Mathematical Sciences (MIMS)



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Faculty of Science

Chiang Mai University, Thailand

# Q & A

ありがとうございました！  
謝謝 Thank You for Your Kind Attention

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